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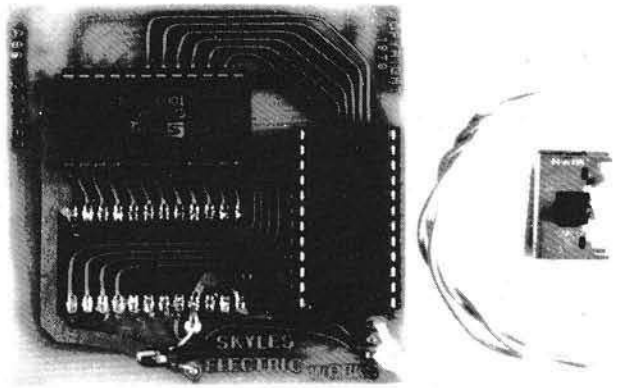

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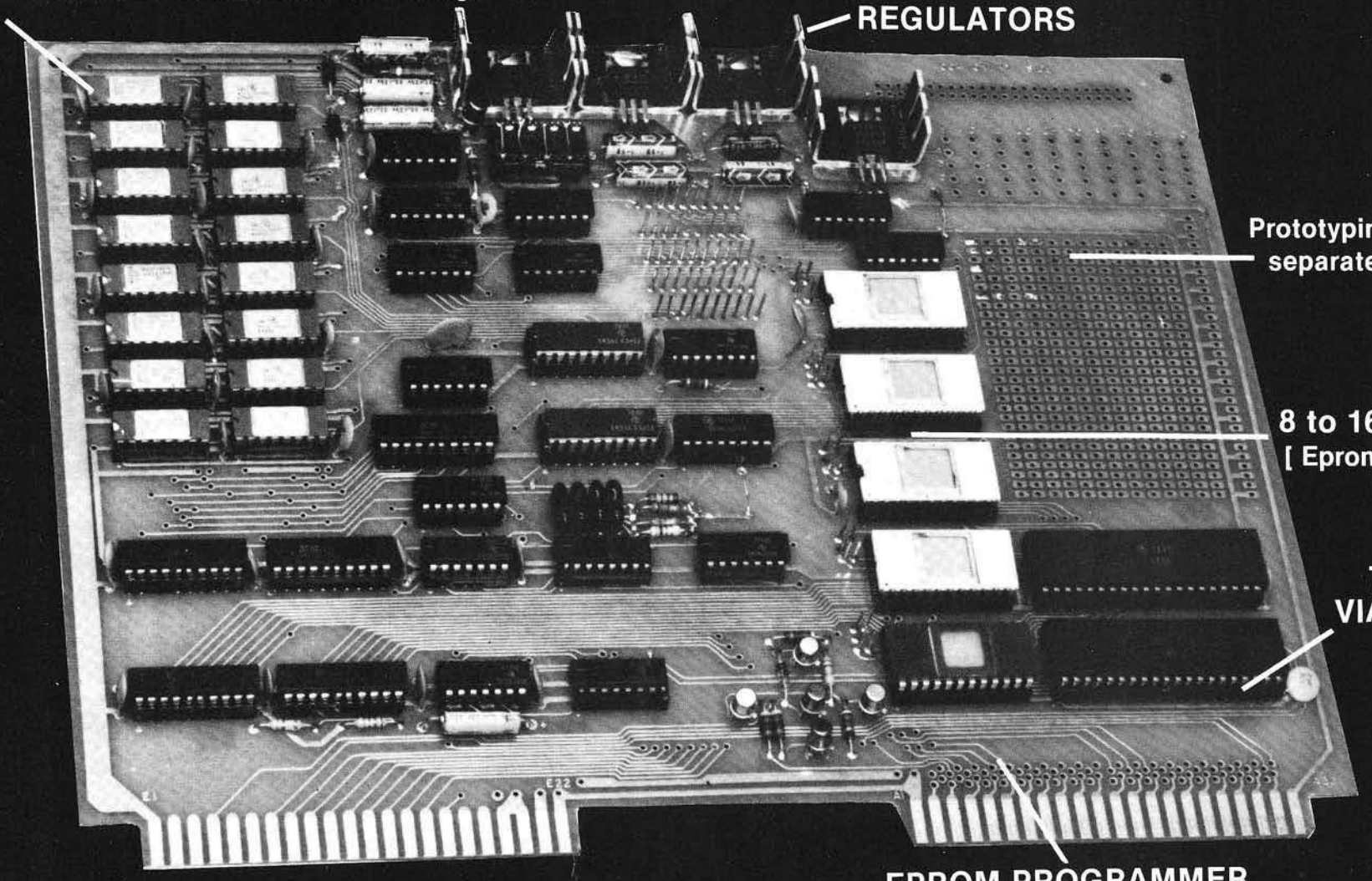
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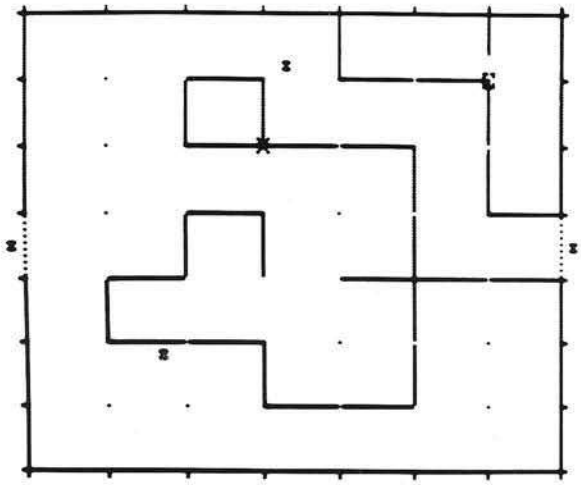

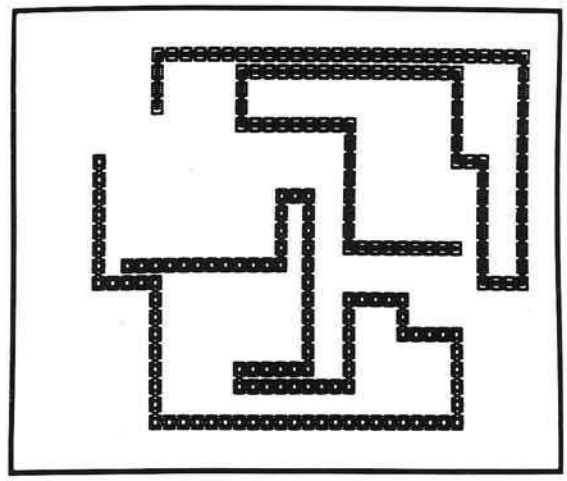

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A 16 Bit 6502?

Several microprocessor manufacturers who make 8 bit micros have recently come out with 16 bit versions or variations. Some of these are true 16 bit micros and some might be best termed "pseudo" 16 bit, that is micros that are basically 8 bit and have an 8 bit data bus, but which can perform some 16 bit operations. There has been talk from time to time about a pseudo 16 bit version of the 6502. It has even had a number, 6509 or 6516, but at present it looks as though it is only a designer's dream.

If someone were to come up with a pseudo 16 bit version of the 6502, what should it contain? And, is there really a need for such a device? I have a few ideas on these matters which I will present next month. An article by Randall Hyde will describe in detail the specifications which were generated for a Synertek 6516. Between now and then, why don't you think about these topics and see what you would like to have in a 16 bit version of the 6502? Maybe with enough input from various sources we can help get such a project moving.

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If you have applied to be a reviewer for the **MICROscope** product review, thank you. We will be sending out acknowledgements and additional information this month. A number of products have been submitted for review, so we will be getting these out to the reviewers soon, and the first **MICROscope** should appear within a couple of months. If you have a product to be reviewed: hardware, software, book, or whatever, contact us for the proper forms.

Robert M. Tripp

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APPLE II Floating Point Utility Routines

Here is a guide to the Applesoft BASIC floating point utility routines which will permit them to be used effectively from assembly language programs. Get the best of both worlds: optimize your programs by writing them in assembly, and, use these excellent floating point math routines directly.

Harry L. Pruetz
2213A Lanier Drive
Austin, TX 78758

Although floating point capabilities are available in Applesoft BASIC, it is still useful to do floating point operations from machine language. This is especially true when the floating point operations are needed at some point in a machine language routine and it would be very tedious to pass parameters back up to a FP BASIC program. The alternative of writing special machine language routines for the solution of a few calculations can also delay a programming project unnecessarily. The purpose of this article is to give an idea of how the AFPUR (Apple Floating Point Utility Routines) work and how to use them.

AFPUR uses 248 bytes from $F425 to$F4FB and the FIX and underflow routines from $F63D to $F65D. In case of overflow, a jump to OVLOC ($3F5) is taken, where a jump to your own code should be stored. Floating Point work space is given in the reference manual as $FO to $FF although only $F3 to $FF are used. The floating point work space bytes and their uses are given in Table 1

E is an extra copy of the FPI mantissa saved during all arithmetic operations although it is actually used only in division. EG is an extra byte changed by the align and normalize code when FP1 and FP2 are being shifted. FP = X,H,M,L is the floating point format of a number where X is the exponent and H, M, and L are the high, medium, and low bytes of the mantissa. Note that the order of the bytes according to significance is opposite that in Integer and FP BASIC and the Sweet 16 interpreter.

The floating point format is similar to 32-bit hardware on many larger computers. The exponent is excess 128 so that $80 represents 2^0. The mantissa is two complement normalized until the two leading bits are different so that + 1.0 = $80 40 00 00 and —1.0 = $7F 80 00 00. Here are some more examples of decimal numbers in hex floating point format:

```
0.0 = $00 00 00 00
1.5 = $80 60 00 00
1.75 = $80 70 00 00
10.0 = $83 40 00 00
256.0 = $88 40 00 00
0.1 = $7C 66 66 66
```

Note that the floating point form $7C 66 66 66 is a truncated approximation of 0.1 so that 0.1 multiplied by 10.0 will give $7F 7F FF FE instead of $80 40 00 00. The AFPUR will work on unnormalized numbers although there can be a loss of accuracy because of the way the alignment code works. For example, in adding the numbers $7F 80 00 00 and $69 40 00 00, the result is $7F 80 00 00 + $7F 00 00 01 = $7F 80 00 01. Using the unnormalized $80 C0 00 00 would give $80 C0 00 00 + $80 00 00 00 = $7F 80 00 00. These cases give trivial losses of accuracy, but more extreme cases can make your Apple II seem like it can't add. Since results of arithmetic operations are normalized in all cases, unnormalized numbers can only be input to the AFPUR by the programmer in the form of stored constants.

Table 2 gives a general idea of how the AFPUR works.

Trying to POKE or PEEK from Integer BASIC will not work because critical information is stored in the same locations as the floating point work space. For example, $F6 and $F7 contain the current Integer BASIC line number and $F8 contains the automatic line numbering mode flag. If a machine language routine is called from Integer BASIC and AFPUR routines are used, then location $F8 should be set to 0 before returning to the Integer BASIC program.

In the following examples of calls to AFPUR, FP1 and FP2 are used as the 4-byte FP registers at $F8 and $F4. If you can try the monitor calls on your Apple II, the examples will be more instructive.

FCOMPL is called by FSUB one time, FMUL two or three times, and FDIV two or three times. It may be called directly by the user. The only FP number which can cause an overflow error is $FF 80 00 00. FCOMPL is easy to use from the monitor:

```
*F8:80 60 00 00
*F8.FB F4A4G F8.FB.
```

An example of a call to give A = — A can be coded by the steps:

```
*0) Declare hex storage as a hex
string
A       .HS 00000000
*1) Load FP1 with A
        LDX #3
LDAL    LDA A,X
        STA FP1,X
        DEX
        BPL LDAL
```

```
*2) Floating complement the number
        JSR $F4A4    FCOMPL
*3) Store FP1 in A
        LDX #3
STAL    LDA FP1, x
        STA A,X
        DEX
        BPL STAL
```

FLOAT of a fixed point number assumes a 15-bit signed integer in M1H and M1M and an 8-bit fraction in M1L. If no fraction is intended, then M1L must be set to $00. FLOAT is a special entry point preceeding normalization code and is called no other place in APFUR. FLOAT is solely for the user. Because of the 15-bit limit on the magnitude of the integer, there can be no overflow errors.

An example of using FLOAT from the monitor is:

```
*F9:00 64 00
*F8. FB F451G F8.FB.
```

An example of a call to give FPA = float (IA) can be coded by the steps:

```
*0) Declare hex strings for IA and FPA
IA      .HS 0000
FPA     .HS 00000000
*1) Load IA into M1
        LDA IA + 1 Intg high byte
        STA M1H
        LDA IA Intg low byte
        STA M1M
        LDA #0
        STA M1L
*2) Float the integer
        JSR $F451  FLOAT
*3) Store FP1 into FPA
        LDX #3
STAL    LDA FP1, X
        STA FPA, X
        DEX
        BPL STAL
```

The FIX of an FP number returns a 15-bit signed integer in M1H and M1M and an 8-bit fraction in M1L. Depending on the size of the FP number, EH, EM and EL may also contain parts of a fraction which could be useful in some calculation. In the more typical uses of FIX, only M1H and M1M are of practical use. FIX has a flaw in the way it treats negative numbers. The FIX1 ($F63D) entry point must be used for negative FP numbers. Calling FIX for FP numbers with exponents larger than $8E will cause overflow errors. Calling FIX1 for negative FP numbers with $8E 7F FF 00, $8E 80 00 00, or exponents larger than $8E will cause overflow errors. To insure that the overflow routine given later in this article will operate properly, a CLV should preceed all FIX and FIX1 calls. Some examples of fixing FP numbers from the Monitor are:

```
*F8:7F 80 00 00
*F8.FB F63DG F8.FB
*F8:80 7F FF 00
*F8.FB F640G F8.FB
```

An example of using an intermediate routine UFIX to give IA = fix(FPA) is:

```
*0) Declare hex strings for IA and FPA

IA      .HS 0000
FPA     .hs 0000000
*1) General UFIX routine
UFIX    CLV              FOR OVERFLOW PROCESSING
        LDA M1H GET SIGN OF FP1
        BPL UFIM
        JSR $F68D        FIX1 (NEGATIVE FP1)
        RTS
UFIM    JSR $F640        FIX (POSITIVE FP1)
        RTS
*2) Load FPA into FP1
        LDX #3
LDAL    LDA FPA, X
        STA FP1, X
        DEX
        BPL LDAL
*3) Fix the FP number
        JSR UFIX
*4) Store M1 into IA, reversing byte order

        LDA M1M
        STA IA
        LDA M1H
        STA IA + 1
```

Unfortunately, FP2 is sometimes changed depending on the signs and exponents of FP1 and FP2 in routines FADD, FSUB, FMUL, and FDIV. Thus, if FP2 is a constant being used in a series of calculations, it would be wise to restore FP2 each time.

An overflow error can occur in the FSUB call to FCOMPL. FP1 can be corrected and control returned to FSUB. FADD and FSUB may both have overflow errors after the operation is completed and normalization is being done. FP2 and FP1 are swapped (interchanged) if FP1 has the larger exponent since alignment operates by shifting the mantissa of FP1 right until the exponents X1 and X2 are equal.

An example of using FADD and FSUB from the monitor is:

```
*F4:81 40 00 00 80 40 00 00
*F0.FF F46EG F0.FF
*F4:81 40 00 00 80 40 00 00
*F0.FF F468G F0.FF
```

FMUL and FDIV both call FCOMPL to get the absolute value of the operand in FP1. This is done by swapping FP1 and FP2, taking the absolute value of FP1, swapping FP1 and FP2 again, and taking the absolute value of FP1 again. The sign of the result (product or quotient) is stored at location $F3 in the right-most bit. Before returning to the user's program, the sign is tested and FCOMPL is called if bit 0 of SIGN is set. An overflow error can occur on any of these FCOMPL calls if FP1 is $FF 80 00 00. Both FMUL and FDIV check for overflow and underflow when calculating the exponent of the unnormalized result. Underflow is handled by UNDFL at $F657 and overflow by the user's own routine.

Table 1

ADDR	NAME	USE
$F3	SIGN	Product/Quotient sign
$F4	X2	FP2 exponent
$F5	M2H	FP2 mantissa high byte
$F6	M2M	FP2 mantissa medium byte
$F7	M2L	FP2 mantissa low byte
$F8	X1	FP1 exponent
$F9	M1H	FP1 mantissa high byte
$FA	M1M	FP1 mantissa medium byte
$FB	M1L	FP1 mantissa low byte
$FC	EH	M1H copy
$FD	EM	M1M copy
$FE	EL	M1L copy
$FF	EG	garbage

Table 2

ADDR	ROUTINE	OPERATION	TIME
$F46E	FADD	FP1 = FP2 + FP1	1.5 millisec
$F468	FSUB	FP1 = FP2 − FP1	1.6 millisec
$F48C	FMUL	FP1 = FP2*FP1	3.5 millisec
$F4B2	FDIV	FP1 = FP2/FP1	5.6 millisec
$F451	FLOAT	FP1 = float(M1)	105 microsec
$F640	FIX	M1 = fix(FP1)	125 microsec
$F4A4	FCOMPL	FP1 = − FP1	135 microsec

FP constants may be calculated by using the monitor as in finding 29.43. The steps are:

1) load M1M with 43 = $2B
2) float
3) move FP1 to FP2
4) load M1M with 100 = $64
5) float
6) divide giving FP1 = float (43)/float (100)
7) move FP1 to FP2
8) load M1M with 29 = $1C
9) float
10) add giving FP1 = 29.43
*F8:00 00 2B 00 F8.FF
*F451G F4 F8.FBM F0.FF
*F8:00 00 64 00 F8.FF
*F451G F4B2G F4 F8.FBM F0.FF
*F8:00 00 1C 00 F8.FF
*F451G F46EG F0.FF

The final result is FP1 = $84 71 B8 51 or 29.43.

As is obvious to the most casual observer, calculating very many constants using the monitor is hazardous to your enthusiasm.

The order in which operands are loaded in FP1 and FP2 for addition and multiplication can be chosen so that the user's code is more efficient. For example, the statement D = A*B + C can be coded by the steps:

```
*0) Declare hex strings for A,B,C,D
A       .HS 80 60 00 00  1.5
B       .HS 82 40 00 00  4.0
C       .HS 7F 80 00 00  -1.0
D       .HS 00 00 00 00
*1) Load FP1 with A
        LDX #3
LDAL    LDA A,X
        STA FP1.X
        DEX
        BPL LDAL
*2) Load FP2 with B
        LDA #3
LDBL    LDA B,X
        STA FP2,X
        DEX
        BPL LDBL
*3) Multiply with product left in FP1
        JSR $F48C
*4) Load FP2 with C
        LDX #3
LDCL    LDA C,X
        STA FP2,X
        DEX
        BPL LDCL
*5) Add with sum left in FP1
        JSR $F46E
*6) Store answer in D
        LDX #3
STDL    LDA FP1,X
        STA D,X
        DEX
        BPL STDL
```

The statement D = A/B - C can be coded by the steps:

```
*7) Load FP2 with A and FP1 with B
        LDX #3
LABL    LDA A,X
        STA FP2,X
        LDA B,X
        STA FP1,X
        DEX
        BPL LABL
*8) Divide leaving the result in FP1
        JSR $F4B2
*9) Move FP1 to FP2 and load FP1 with C
        LDX #3
LDCL    LDA FP1,X
        STA FP2,X
        LDA C,X
        STA FP1,X
        DEX
        BPL LDCL
*10) Subtract leaving the difference in FP1
        JSR $F468
*11) Store the answer in D
        LDX #3
STDL    LDA FP1,X
        STA D,X
        DEX
        BPL STDL
```

All of the overflow errors detected in the AFPUR jump to OVLOC and then to the user's code. When CLV is used before fixing a FP number, the status register bits N,V,Z can be used to determine the routine where the error occured. Table 3 demonstrates this.

Table 3

Routine	N V Z	EOR Test	STK
FIX	0 0 1	$02	0
FIXL	0 0 1	$02	0
FCOMPL	0 1 1	$42	0
FADD	0 1 1	$42	0
FSUB	0 1 1	$42	0
FMUL	1 0 0	$80	2
FDIV	1 0 0	$80	2

The routine in Listing 1 determines which minimum or maximum integer or FP number to store in FP1 before returning to the AFPUR. The contents of the status register and the AFPUR return address are stored in locations $F0, $F1, $F2.

The times for the AFPUR given at the first of this article are for the routines themselves. As can be seen by the previous examples, much more code is required to make practical use of the AFPUR. Two fairly simple programs were used to time the AFPUR. The program used to time FADD consisted of summing the floated values of the integers 1 to 32,768. The program required about 55 seconds to get $9C 7F 64 00, which is close to $5.37*10^8$. Part of the time was spent in the FLOAT routine and the summing program itself. A listing of the program is given in Listing 2.

The relative offsets of labels from SUMI are ZL = $04, INC2 = $0A, FLT = $2D, SL = $3E and IH = $49.

The program used to time FMUL consisted of summing a geometric progression with a factor close to 1.0. The multiplications involved calculating the next term in the sequence. For a factor too close to 1.0, the loss of accuracy in the floating point operations gave an incorrect answer. However, for factors like $80 3F FF F0, the answer was close enough. A listing of the program for finding $(1 - R^N)/(1 - R) = 1 + R + ... + R^N$ is given in Listing 3.

The code in the AFPUR demonstrates many useful machine language programming tricks. I also think too much speed was sacrificed to get a minimum amount of code. Although the floating point format used is fairly standard, the methods used would work better with a signed magnitude floating point format so that negative operands could be easily complemented before multiplication or division.

Finally, a 3-byte floating point format would be entirely sufficient such that integers and FP numbers had the same byte order for many machine language programming applications.

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Listing 1

```
            *        OVFL
          *AFPUR OVERFLOW ROUTINE
*
        .OR $3F5
        JMP OVFL
        .OR $900
SIGN    .EQ $F3
FP1     .EQ $F8
OVFL    PHP         SAVE STATUS
        PLA
        AND #$C2
        STA $F0     STORE STATUS
        PHA
        EOR #$80
        BEQ MLDV    MULTIPLY/DIVIDE
        PLA
        EOR #$42
        BEQ ADSB    ADD/SUBTRACT
*FIX    OVERFLOW--SIGN BIT IN C
        BCS FIXM
        LDX #3      INTEGER MINIMUM
        BPL OVST
FIXM    LDX #7      INTEGER MAXIMUM
        BPL OVST
*MULTIPLY/DIVIDE OVERFLOW--SIGN BIT IN SIGN
MLDV FOR SIGN
        PLA         ADJUST STACK
        PLA
*ADD/SUBTRACT OVERFLOW--SIGN BIT IN C
ADSB BCS ASM
        LDX #11     FP MINIMUM
        BPL OVST
ASM     LDX #15     FP MAXIMUM
*STORE OVERFLOW VALUE IN FP1 FOR ALL CASES
OVST    LDY #3
OVSL    LDA OTBL,Y
        STA FP1,Y
        DEX
        DEY
        BPL OVSL
*SAVE AFPUR RETURN ADDRESS
        CLV         CLEAR V STATUS BIT
        PLA
        STA $F1
        INC 1F1
        PLA
        STA $F2
        JMP ($F1)
OTBL    .HS 8E7FFF00
        .HS 8E800100
        .HS FF7FFFFF
        .HS FF800001
```

Listing 2

```
*       SUMI
*SUM INTEGERS PROGRAM
*
        FP1 .EQ  $F8
        FP2 .EQ  $F4
        M1  .EQ  $F9
SUMI    LDX #6      ZERO IH THROUGH S
        LDA #0
ZL      STA IH,X
        DEX
        BPL ZL
INC2    INC IM      INCREMENT IM AND IH
        BNE FLT
        INC IH      INCREMENT IH EVERY 256 ITERATIONS
        LDA IH
        CMP #$80
        BNE INC2
        RTS
*LOAD INTEGER INTO M1
FLT     LDA IH
        STA M1
        LDA IL
        STA M1+1
        LDA #0
        STA M1+2
        JSR $F451 FLOAT
        LDX #3      ADD INTEGER TO SUM
AL      LDA FPI,X
        STA FP2,X FP2=FP1
        LDA S.X
        STA FP1,X FP1=S
        DEX
        BPL AL
        JSR $F46E FADD
        LDX #3      SAVE SUM
SL      LDA FP1,X
        STA S,X     S=FP1
        DEX
        BPL SL
        JMP INC2
IH      .DA #0      INTEGER HIGH BYTE
IM      .DA #0      INTEGER MIDDLE BYTE
IL      .DA #0      INTEGER LOW BYTE
S       .HS 00000000          SUM
```

Listing 3

```
        GSUM
 *GEOMETRIC PROGRESSION SUM
 *
 FP1    .EQ $F8
 FP2    .EQ $F4
        .OR $800
 GSUM   LDX #6      ZERO I AND S
        LDA #0
 ZL     STA IH,X
        DEX
        BPL ZL
 *S E T T = 1.0
        LDA #$40
        STA T
        LDA #$40
        STA T +1
        LDA #0
        STA T+2
        STA T+3
 *S T   R = 1.0 - 2 (-18)
        LDA #$80
        STA R
        LDA #$3F
        STA R+1
        LDA #$FF
        STA R+2
        LDA #$F0
        STA R+3
 *INCREMENT IM AND IH
 INC2 INC IM
        BNE CALC
        INC IH
        LDA IH
        CMP #$80
```

```
        BNE INC2
        RTS
*LOAD S AND T FOR ADD
CALC    LDX #3
AL      LDA S,X
        STA FP1,X    FP1=S
        LDA T,X
        STA FP2,X    FP2=T
        DEX
        BPL AL
        JSR $F46E    FADD S+T
*SAVE S
        LDX #3
SL      LDA FP1,X
        STA S,X
        DEX
        BPL SL
*LOAD T AND R FOR MULT
        LDX#3
ML      LDA T,X
        STA FP1,X    FP1=T
        LDA R,X
        STA FP2,X    FP2=R
        DEX
        BPL ML
        JSR $F48C    FMUL R*T
*SAVE T
        LDX #3
TL      LDA FP1,X
        STA T,X
        DEX
        BPL TL
        JMP INC2
IH      .DA #0       LOOP INDEX HIGH
IM      .DA #0       LOOP INDEX MIDDLE
S       .HS 00000000SUM
T       .HS 00000000TERM
R       .HS 00000000FACTOR
```

A JSR FDIV was substituted in this program to get the FDIV timing.

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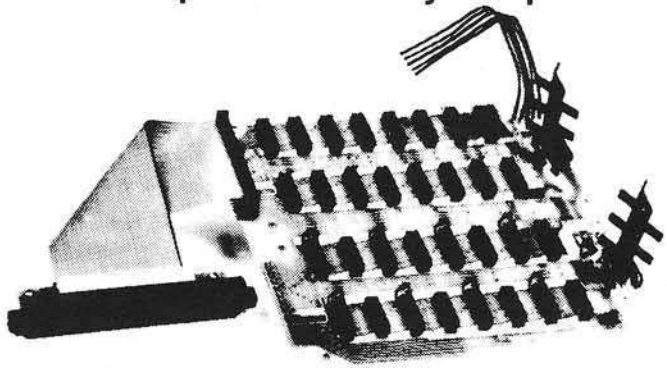

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A Machine Language Screen Print Program- for the Old (or New) PET

A program is presented which gives the user control over printing from the old PET screen. The commented assembly language program provides information on printing and can be used as a starting point for other print utilities.

Kenneth Finn
Little Old Farm
Bedford, NY 10506

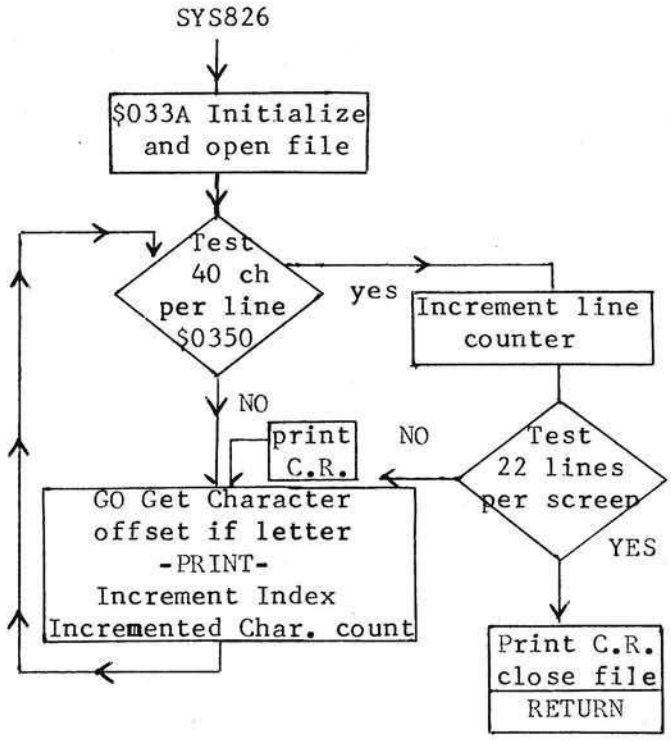
After waiting almost a year, I finally received the dot matrix, friction feed printer for the Commodore PET. The printer plugs right into the IEEE port and will print all the PET graphics as well as upper and lower case letters.

When I received the printer, I also got some very scanty documentation. What I learned from it is that you can print in your programs by using PRINT# statements after OPEN-ing the file. I also learned that you could set up the printer as the primary device by using the following code:

```
OPEN 4,4,0 : CMD 4
```

This is fine to have the printer print *everything* that would be on the screen but still not very good if you just want to print *some* things.

What I needed was a short program that would print what was on the screen when I wanted it printed. This dictated a machine language program stored in the second cassette buffer that I could call with a *SYS826* when I wanted anything printed. After some trepidation and a lot of help from other programs, the following is the result. It can reside in the second cassette buffer and will print the *top 22 lines* of the screen at *40 characters per line* when you want it.



```
033A  A9 00        LDA  #$00
033C  8D 56 02     STA  $ 0256     Printer Secondary Address
033F  8D FE 03     STA  $ 03FE     Screen Line Counter
0342  8D FF 03     STA  $ 03FF     Character counter
0345  85 DA        STA  $ DA       Index Lo-Byte
0347  A9 01        LDA  #$01
0349  8D 62 02     STA  $ 0262     GPIB File Length
034C  A9 04        LDA  #$04
034E  8D 42 02     STA  $ 0242     Logical File #
0351  8D 4C 02     STA  $ 024C     Device Number
0354  A2 04        LDX  #$04
0356  20 C9 FF     JSR  $ FFC9     Open File (i.e. Open 4,4,0)
0359  A9 80        LDA  #$80
035B  85 DB        STA  $ DB       Index Hi-Byte
035D  AD FF 03     LDA  $ 03FF
0360  C9 28        CMP  #$28       40 Characters per line, test
0362  D0 14        BNE  $ 0378     (GO)
0364  EE FE 03     INC  $ 03FE     Increment Line Counter
0367  AD FE 03     LDA  $ 03FE
036A  C9 16        CMP  #$16       22 lines/screen test
036C  F0 23        BEQ  $ 0391      (END)
036E  A9 00        LDA  #$00
0370  8D FF 03     STA  $ 03FF
0373  A9 0D        LDA  #$0D       C.R. in ASCII
0375  20 30 F2     JSR  $ F230     Print #4,C.R.
0378  18        (GO)CLC
0379  A2 00        LDX  #$00
037B  A1 DA        LDA  ($DA,X)    Get next character via indirect addr.
037D  C9 1F        CMP  #$1F        Test for Letter
037F  10 02        BPL  $ 0383
0381  69 40        ADC  #$40       Offset for Pet screen to ASCII
0383  20 30 F2     JSR  $ F230      Print #4
0386  E6 DA        INC  $ DA       Increment index Lo-byte
0388  D0 02        BNE  $ 038C     Branch if not zero
038A  E6 DB        INC  $ DB        Increment Index Hi-byte
038C  EE FF 03     INC  $ 03FF     Increment Character counter
038F  10 CC        BPL  $ 035D     Return for next character
0391  A9 0D      (end)LDA  #$0D     Ascii C.R.
0393  20 30 F2     JSR  $ F230     Print #4
0396  A9 04        LDA  #$04
0398  20 CC FF     JSR  $ FFCC     Close 4
039B  60           RTS             Return
```

```
. $ 033A,039B
.       |  0  1  2  3  4  5  6  7
.  033A | A9 00 8D 56 02 8D FE 03
.  0342 | 8D FF 03 85 DA A9 01 8D
.  034A | 62 02 A9 04 8D 42 02 8D
.  0352 | 4C 02 A2 04 20 C9 FF A9
.  035A | 80 85 DB AD FF 03 C9 28
.  0362 | D0 14 EE FE 03 AD FE 03
.  036A | C9 16 F0 23 A9 00 8D FF
```

```
. $ 033A,039B
.       |  0  1  2  3  4  5  6  7
.  0372 | 03 A9 0D 20 30 F2 18 A2
.  037A | 00 A1 DA C9 1F 10 02 69
.  0382 | 40 20 30 F2 E6 DA D0 02
.  038A | E6 DB EE FF 03 10 CC A9
.  0392 | 0D 20 30 F2 A9 04 20 CC
.  039A | FF 60 EA EA EA EA EA EA
.
```

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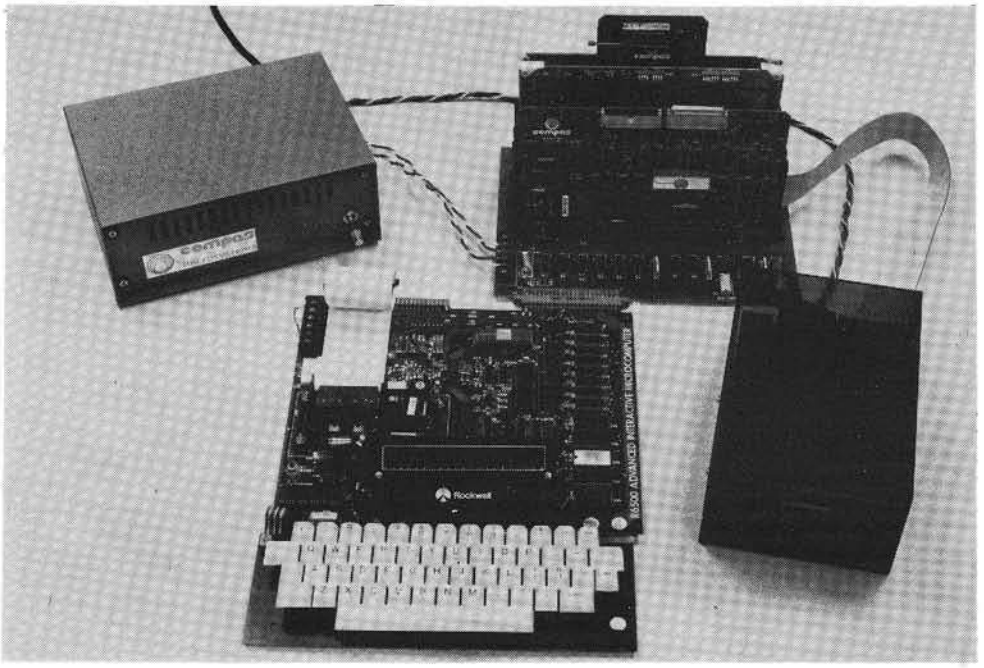

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OSI machines come with a polled keyboard arranged in the standard 53 key format. Each key is a switch whose state (open or closed) can be ascertained under software control. Polled keyboard hardware affords maximum flexibility to the programmer. The most immediate use of the keyboard is for input to BASIC and other standard software which expects letters to be ASCII capitals but numbers and symbols to be unshifted. For this reason, the keyboard ROM in OSI machines has been programmed to yield capital letters and unshifted numbers when the SHIFT LOCK key is depressed. I am writing an editor program and desire the keyboard to act in the conventional "typewriter" manner with respect to shifting. The Program Listing gives a subroutine (lines 80 to 730) for returning the standard ASCII from the keyboard, and a driver program (lines 10 to 70) to demonstrate the subroutine. As a bonus, all the function keys (ESC, etc.) ignored by the OSI ROM are implemented to yield standard ASCII code.

When called, the subroutine loops until a key (other than SHIFT or CTRL) is depressed, then returns with the appropriate ASCII code in bits 0 through 6 of the accumulator. If CTRL was also depressed, bit 7 in the accumulator is set (1), otherwise it is reset (0). Except for the CTRL and SHIFT keys, the routine expects only one key to be depressed at a time. The routine detects the first character key depressed if several are depressed at the same time. The subroutine clobbers the X register.

Several choices have been made which you can easily change. The SHIFT LOCK key is ignored. The program works the same whether it is depressed or not. AND #7 in line 540 will enable the SHIFT LOCK key. LEFT and RIGHT SHIFT keys are made equivalent, just as on a typewriter. Since REPT is not an ASCII signal, I chose the code $00 for it arbitrarily. The BREAK key on OSI machines is hard wired to the reset line of the 65XX chips and so is not detectable by this program. ESC, RUB OUT, LINE FEED, and RETURN have ASCII codes $1B, 7F, 0A, and 0D respectively.

The keys are arranged electrically as an 8x8 matrix. I will not discuss this matrix in detail. It is shown in the OSI Graphics Manual. The first row of the matrix contains only control keys: LEFT SHIFT, RIGHT SHIFT, SHIFT LOCK, REPT, CTRL, and ESC. I call this row CTLROW and read it first. If the REPT or ESC keys are depressed, the program returns immediately with the appropriate code. If not, CTLROW is saved and rows 2 through 8 are polled for character keys. RUB OUT, LINE FEED, and RETURN are included among the character keys. When shifted, they give $20 "space" as their code. You could change line 730 so that some other ASCII function not represented on the keyboard (for example, $07 "bell") would be signaled. The polling for character keys continues in a loop until a key closure is detected. Then its ASCII code is put in the accumulator. If a SHIFT key is down, the shifted code is put in the accumulator. Then the CTRL key closure is tested. Bit 7 of the accumulator is set if appropriate.

All this happens in a millisecond or so. Many uses of the subroutine will require a check to see if the keyboard is clear of the old keystroke so that a new keystroke can be sought. The KYDONE subroutine (lines 740 to 780) accomplishes this. Once entered, KYDONE (ignoring the CTLROW keys) loops until there are no depressed keys on the keyboard, then returns.

A modified KYDONE could be a useful element in a more sophisticated keyboard program. One may wish to implement the repeat-after-a-delay mode that OSI uses in its keyboard routine. Or a two-key-rollover mode can be implemented which allows recovery from errors induced by fast, sloppy typing.

Listing 1

```
 10 0000                    LOC=$D000+256
 20 C200                    *=$C200
 30 C200 2000C0   MAIN      JSR KYBD
 40 C203 8D00D1             STA LOC
 50 C206 20D7C0             JSR KYDONE
 60 C209 D0F5               BNE MAIN
 70 C20B F0F3               BEQ MAIN
 80 C20D                    KYPORT=$DF00
 90 C20E                    CTLROW*=*+1
100 C20F                    ACC*=*+1
110 C210                    XREG*=*+1
120 C000                    *=$C000
130 C000 A901    KYBD      LDA #1
140 C002 D00DF             STA KYPORT     LOOK FOR CONTROL KEYS
150 C005 AD00DF            LDA KYPORT
160 C008 8D0DC2            STA CTLROW
170 C00B 18                CLC
180 C00C 0A                ASL A          IS IT 'REPT'?
190 C00D 9003              BCC KY1        NO, BRANCH
200 C00F A900              LDA #0         YES
210 C011 60                RTS
220 C012 0A      KY1       ASL A          SKIP 'CTRL' FOR NOW
230 C013 18                CLC
240 C014 0A                ASL A          IS IT 'ESC'
250 C015 9003              BCC KY2        NO, BRANCH
260 C017 A91B              LDA #$1B       YES
270 C019 60                RTS
280 C01A A902    KY2       LDA #2         LOOK FOR CHAR. KEYS
290 C01C 8D00DF  KYBD1     STA KYPORT
300 C01F AE00DF            LDX KYPORT
310 C022 D005              BNE CHR
320 C024 0A                ASL A
330 C025 D0F5              BNE KYBD1
340 C027 F0D7              BEQ KYBD       NONE FOUND, LOOK AGAIN
350 C029 8D0EC2  CHR       STA ACC        WHICH ROW
360 C02C 8E0FC2            STX XREG       WHICH COL.
370 C02F 18      CHR1      CLC
380 C030 A900              LDA #0         DECODE MATRIX
390 C032 4E0EC2            LSR ACC
400 C035 4E0EC2  SHIFT     LSR ACC
410 C038 B004              BCS FNDROW
420 C03A 6907              ADC #7
430 C03C 90F7              BCC SHIFT      BRANCH ALWAYS
440 C03E 18      FNDROW    CLC            FOUND ROW, WHICH COL.?
450 C03F 4E0FC2            LSR XREG
460 C042 4E0FC2  SHIFT2    LSR XREG
470 C045 B004              BCS FNDCOL
480 C047 6901              ADC #1
490 C049 90F7              BCC SHIFT2
500 C04B AA      FNDCOL    TAX            FOUND COL., STORE
510 C04C BD75C0            LDA CHRTBL,X
520 C04F 8D0EC2            STA ACC
530 C052 AD0DC2            LDA CTLROW
540 C055 2906              AND #6         IS IT A L. OR R. SHIFT?
550 C057 F00B              BEQ KY3        NO, BRANCH
560 C059 18                CLC            YES

570 C05A 8A                TXA
580 C05B 6931              ADC #49
590 C05D AA                TAX
600 C05E BD75C0            LDA CHRTBL,X
610 C061 8D0EC2            STA ACC        CAP. CHAR. IN ACC
620 C064 AD0DC2  KY3       LDA CTLROW
630 C067 2940              AND #$40       IS IT 'CTRL'?
640 C069 F006              BEQ KY4        NO, BRANCH
650 C06B AD0EC2            LDA ACC        YES
660 C06E 0980              ORA #$80       BIT 7 OF CHAR. IS SET
670 C070 60                RTS            RETURN WITH CHAR. IN A
680 C071 AD0EC2  KY4       LDA ACC
690 C074 60                RTS            RETURN WITH CHAR. IN A

700 CHRTBL .BYTE'p;/ zaq,mnbvcxk jhgfdsiuytrew'
710        .BYTE'  ',$0D,$0A,'ol. ',$7F,'-:0987654321'
720        .BYTE'P+? ZAQ<MNBVCXKJHGFDSIUYTREW'
730        .BYTE'    OL>  =*0)(''&%$#"!'

740 C0D5 A9FE    KYDONE    LDA #$FE       IS KEY STROKE OVER?
750 C0D7 8D00DF            STA KYPORT
760 C0DA AD00DF            LDA KYPORT
770 C0DD D0F6              BNE KYDONE
780 C0DF 60                RTS            KEY IS RELEASED
```


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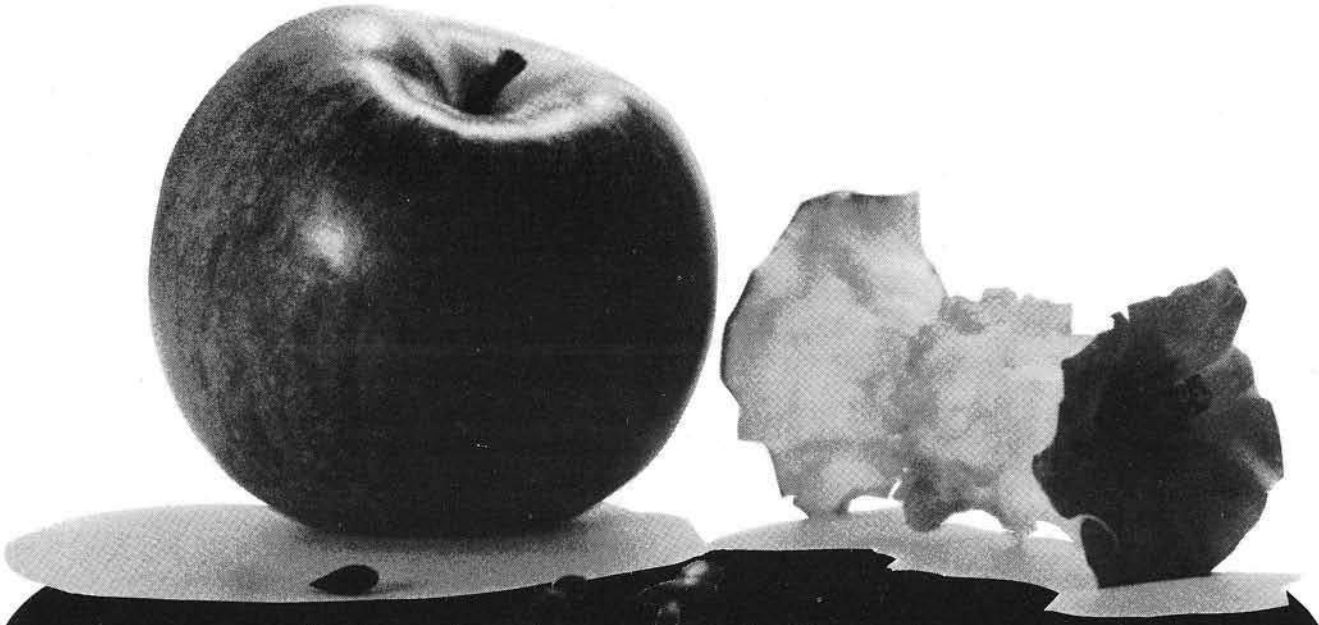

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A Digital Thermometer for the APPLE II

Thermistor probes can be connected directly to the APPLE II Game I/O Connector and their output signals processed via a linearizing algorithm to produce a digital display in both degrees Celsius and Fahrenheit.

Carl J. Kershner
2123 Timberidge Circle
Dayton, OH 45459

Thermistor probes can be connected directly to the APPLE II Game I/O Connector and their output signals processed via a linearizing algorithm to produce a digital display in both Celcius and Fahrenheit.

A thermistor temperature measuring probe can be directly connected to the APPLE II computer via its built-in Game I/O Connector. This is possible since thermistors are "thermal resistors" which exhibit large resistance changes in response to a change in temperature and paddle input ports, PDL(0,1,2,&3), on the APPLE are essentially eight bit A/D converters for such variable resistance sources.

The APPLE and the thermistor are quite suited for one another since the inherent nonlinearity of the thermistor can be easily handled with a simple algorithm in software. In addition, the small current drain during the sampling cycle of the RC network on the APPLE's 553 timer closely approaches the ideal zero-power operating condition for a thermistor. Both the nonlinearity and the induced temperature due to the probing current have been particularly troublesome characteristics which engineers have had to find ways of working around when applying thermistors.

The program written in Applesoft consists of an input section, a data reduction section and a display section. The input section calls for the selection of a paddle input and two thermistor spacifications used by most manufacturers; the room temperature resistance designated as RO and a value representing the ratio of the resistance at 25°C to that at 50°C designated as RA. The selected paddle input is then read and scaled to represent the resistance value at the input port. The corresponding temperature in both degrees Celcius and Fahrenheit are calculated from the resistance via a temperature-resistance relationship:

$$R_1/R_2 = e^{\beta(1/T_1 - 1/T_2)}$$

where R_1 and R_2 are the resistances at the absolute temperature T_1 and T_2 respectively, and β is a constant for the particular thermistor material. The results are rounded to the nearest integer and displayed in a three digit format with the blanking of leading zeros and a negative sign for temperatures belwo zero.

A thermistor probe can be connected to the APPLE II by merely attaching one of its leads to the +5 volt supply, pin 1, and the other to one of the PDL ports, pins 6,7, 10, or 11 on the Game I/O connector J 14. No other components or modifications are required so long as a thermistor is chosen with a room temperature resistance and ratio which suits the temperature range and sensitivity desired for application. A 40,000 ohm thermistor with a ratio of 9 or 10 will provide at least one degree Fahrenheit sensitivity and a working range suitable for an indoor thermometer application. The best way to choose a thermistor for your particular application is to run the program using a game paddle as input, enter values for RO and the RA from a manufacturer's specification sheet, and observe the useful operating range and sensitivity of the selected thermistor. This latted proceedure demonstrates the additional usefulness of the program as an engineering design aid in selecting thermistor for other applications.

Thermistors suitable for this application can be purchased for less than five dollars from most supply houses or directly from a manufacturer. A Fenwal GA44P2 glass probe type thermistor with a room temperature resistance of 40,000 ohms and a ratio of 9.53 is a good choice for an indoor thermometer application, whereas a Fenwal GA42P2 with a room temperature resistance of 15,000 ohms and a ratio of 9.1 is a good compromise

for indoor-outdoor use. It is best to house the thermistor probe in a small metal tube to protect it from mechanical damage and to provide thermal inertia to minimize effects of short term temperature transients. It is also advisable to calibrate the thermistor probes against a laboratory type thermometer, if high accuracy is desired, because the manufacturing tolerances on RO and RA values for the inexpensive probes described here are generally no better than ± 10%.

Because thermistors can be used that have relatively high resistances, transmission line and contact temperature effects can be neglected and the probes can be situated far from the computer console. Thus the APPLE II digital thermometer can perform many useful temperature monitoring tasks in and around the house.

The Fenwal products mentioned in this article can be purchased from Fenwal Electronics, 63 Fountain St., PO Box 585, Framingham, MA 01701.

```
LIST
100  REM   DIGITAL THERMOMETER FO
     R THERMISTOR PROBE(DISPLAYS
     BOTH CELCIUS &FAHRENHEIT)
110  PRINT "WHICH INPUT DO YOU WA
     NT(0,1,2,3)": INPUT NUMBER
120  PRINT "WHAT THERMISTOR CONST
     ANTS DO YOU WANT(RO,RATIO)":
      INPUT RO,RA
125 BETA = 1.7636E3 *  LOG (RA)
130  HOME : REM   CLEAR SCREEN
140  REM   PRINT TEMPERATURE SCALE
      CHARACTERS
150  GR : COLOR= 15
160  HLIN 26,27 AT 6: HLIN 26,27 AT
     7: HLIN 26,27 AT 9: HLIN 26,
     27 AT 10: VLIN 7,9 AT 25: VLIN
     7,9 AT 28
170  HLIN 34,38 AT 9: HLIN 34,38 AT
     10: HLIN 34,36 AT 14: HLIN 3
     4,36 AT 15: VLIN 9,20 AT 33
180  HLIN 26,27 AT 23: HLIN 26,27
      AT 24: HLIN 26,27 AT 26: HLIN
     26,27 AT 27: VLIN 24,26 AT 2
     5: VLIN 24,26 AT 28
190  VLIN 28,29 AT 38: VLIN 27,28
      AT 37: VLIN 26,27 AT 36: VLIN
     26,27 AT 35: VLIN 27,28 AT 3
     4
200  VLIN 28,35 AT 33: VLIN 35,36
      AT 34: VLIN 36,37 AT 35: VLIN
     36,37 AT 36: VLIN 35,36 AT 3
     7: VLIN 34,35 AT 38
210 T = 298: REM   SET T(0) AT 29
     8 DEGREES ABSOLUTE
220 RI = 589.94 *  PDL (NUMBER): REM
       READ INPUT & SCALE TO OHMS

230  IF RI = 0 THEN RI = 1: REM
      PREVENT DIVISION BY ZERO
240 TC =  INT (1 / (1 / T -  LOG
     (RO / RI) / BETA) - 272.5): REM
       CALCULATE TEMPERATURE IN D
     EGREES CELCIUS AND ROUND TO
     NEAREST INTEGER
245  IF  ABS (TC) > 999 THEN  GOTO
     220: REM   LIMIT OVERFLOWING
      DISPLAY
250 SIGN = 0
260  IF TC < 0 THEN SIGN = 15
270  COLOR= SIGN
280  HLIN 3,5 AT 29: HLIN 3,5 AT
     30: REM   DISPLAY NEGATIVE S
     IGN
290 TC =  ABS (TC)
300 J =  INT (TC / 100):I = J: REM
      SEPARATE HUNDRED'S DIGIT
310  IF J = 0 THEN J = 10: REM
     BLANK LEADING ZERO
320 X = 1:Y = 26: GOSUB 1000: REM
      DISPLAY CELCIUS HUNDRED'S
330 J =  INT ((TC - J * 100) / 10
     ): REM   SEPARATE TEN'S DIGI
     T
340  IF I = 0 AND J = 0 THEN J =
     10: REM   BLANK BOTH HUNDRED
     'S AND TEN'S LEADING ZEROS I
     F J&I ARE BOTH ZERO
350 X = 9:Y = 26: GOSUB 1000: REM
      DISPLAY CELCIUS TEN'S DIGI
     T
360 J = TC - I * 100 - J * 10: REM
      SEPARATE ONE'S DIGIT
370 X = 17:Y = 26: GOSUB 1000: REM
      DISPLAY CELCIUS ONE'S DIGI
     T
380 TF =  INT (9 * (1 / (1 / T -
      LOG (RO / RI) / BETA) - 273
     ) / 5 + 32.5): REM   CALCULA
     TE FAHRENHEIT & ROUND TO NEA
     REST INTEGER
390 SIGN = 0
400  IF TF < 0 THEN SIGN = 15
410  COLOR= SIGN
420  HLIN 3,5 AT 12: HLIN 3,5 AT
     13: REM   DISPLAY NEGATIVE S
     IGN
430 TF =  ABS (TF)
440 J =  INT (TF / 100):I = J: REM
      SEPARATE HUNDRED'S DIGIT
```

```
450  IF J = 0 THEN J = 10: REM
     BLANK LEADING ZERO
460 X = 1:Y = 9: GOSUB 1000: REM
      DISPLAY FAHRENHEIT HUNDRED
    'S DIGIT
470 J =  INT ((TF - J * 100) / 10
    ): REM   SEPARATE TEN'S DIGI
    T
480  IF I = 0 AND J = 0 THEN J =
     10: REM   BLANK BOTH HUNDRED
    'S AND TEN'S LEADING ZEROS
490 X = 9:Y = 9: GOSUB 1000: REM
      DISPLAY FAHRENHEIT TEN'S D
    IGIT
500 J = TF - I * 100 - J * 10: REM
      SEPARATE ONE'S DIGIT
510 X = 17:Y = 9: GOSUB 1000: REM
      DISPLAY FAHRENHEIT ONE'S D
    IGIT
520  GOTO 220
1000  REM   SEVEN SEGMENT ENCODER

1010  ON J GOTO 1110,1120,1130,11
     40,1150,1160,1170,1180,1190,
     1200
1100 A = 15:B = 15:C = 15:D = 15:
     E = 15:F = 15:G = 0: GOTO 20
     00
1110 A = 0:B = 15:C = 15:D = 0:E =
     0:F = 0:G = 0: GOTO 2000
1120 A = 15:B = 15:C = 0:D = 15:E
      = 15:F = 0:G = 15: GOTO 200
     0
1130 A = 15:B = 15:C = 15:D = 15:
     E = 0:F = 0:G = 15: GOTO 200
     0
1140 A = 0:B = 15:C = 15:D = 0:E =
     0:F = 15:G = 15: GOTO 2000
1150 A = 15:B = 0:C = 15:D = 15:E
      = 0:F = 15:G = 15: GOTO 200
     0
1160 A = 15:B = 0:C = 15:D = 15:E
      = 15:F = 15:G = 15: GOTO 20
     00
1170 A = 15:B = 15:C = 15:D = 0:E
      = 0:F = 0:G = 0: GOTO 2000
1180 A = 15:B = 15:C = 15:D = 15:
     E = 15:F = 15:G = 15: GOTO 2
     000
1190 A = 15:B = 15:C = 15:D = 15:
     E = 0:F = 15:G = 15: GOTO 20
     00
1200 A = 0:B = 0:C = 0:D = 0:E =
     0:F = 0:G = 0:J = 0: GOTO 20
     00
2000  REM  SEVEN SEGMENT DISPLAY
2010  COLOR= A
2020  HLIN X + 1,X + 4 AT Y
2030  HLIN X + 1,X + 4 AT Y + 1
2040  COLOR= G
2050  HLIN X + 1,X + 4 AT Y + 5
2060  HLIN X + 1,X + 4 AT Y + 6
2070  COLOR= D
2080  HLIN X + 1,X + 4 AT Y + 10
2090  HLIN X + 1,X + 4 AT Y + 11
2100  COLOR= F
2110  VLIN Y + 1,Y + 5 AT X
2120  COLOR= B
2130  VLIN Y + 1,Y + 5 AT X + 5
2140  COLOR= E
2150  VLIN Y + 6,Y + 10 AT X
2160  COLOR= C
2170  VLIN Y + 6,Y + 10 AT X + 5
2180  RETURN
```


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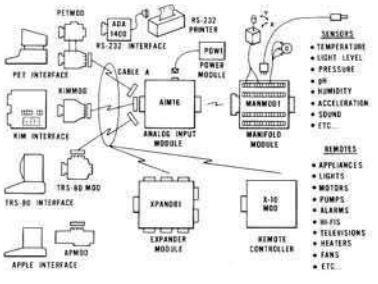

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Challenger II Cassette Techniques

The Challenger II has available a useful feature which allows the storage and retrieval of sequential data files on cassette using SAVE and LOAD commands in a program. This can be used to extend the size of your BASIC programs by permitting DATA to be INPUT from tape as needed.

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Kilausa, HI 96754

Well, I knew it would happen sooner or later. I came across a program which I wished to run on my Challenger II but my 8K of memory was not enough to satisfy the program's appetite.

The desired program used several arrays to store variable values with DATA statements being used to supply the required values for the arrays. After dimensioning the arrays and entering all the required DATA statements, I discovered, much to my dismay, that these two steps had consumed nearly the entire 8K. What to do...?

After staring blankly at the CRT for several minutes wondering what I was going to do, I remembered reading something in my system documentation about entering data files from the cassette interface using the INPUT statement. This seemed to be my only hope to get the program running.

The Challenger II has a useful feature available which allows you to conveniently store and retrieve sequential data files on cassette using SAVE and LOAD commands as part of a program. The remainder of this article will describe a simple method to make use of this feature.

The first step is to store the data in a sequential file on cassette tape. Program 1 shows how this can be done. Program line 20 allows for setup and start of the recorder before the data file is recorded. Line 30 is a programmed SAVE instruction which, when executed, turns on the cassette output such that any ASCII characters listed or printed after the SAVE instruction will be output to the cassette tape. Lines 40-70 form a loop which reads data from lines 100 and 110, prints the data on the screen and outputs the data to the cassette, one variable at a time, each variable being followed by the PRINT command's carriage return.

Program 1 shows how to use DATA statements as the data source. Program 1 can be modified, as shown in Program 2 to load the data variables into an array via the keyboard and INPUT statement and then dump the array variables to the cassette. In Program 2, lines 20-60 input and store the variables in the array "D"; lines 80-110 create the sequential data file on tape as in Program 1. Line 70 allows you to set up and start your recorder before the data file is actually created.

It is very important to insure that there is no unwanted data stored on the cassette tape immediately before the start of the data file because this erroneous data will be mistaken for real data by the program which retrieves the data file. This is easy to accomplish if your recorder erases previous data before it records new data. If your recorder operates in this manner, simply allow the recorder to run in it's record mode for approximately 10 seconds before the save portion of Programs 1 or 2 are executed. Doing so will create a leader free of erroneous data before the start of the data file. If your recorder does not erase before it records, you will have to use a method compatible with your recorder which will erase a portion of the tape before the start of the data file.

After you have recorded your data file using Program 1 or 2, the next task is to retrieve the data.

Program 3 demonstrates a method for retrieving the data. Program 3 will allow you to retrieve the sample data file you created using Program 1. Line 20 dimensions the array into which the data is to be stored as it is retrieved from the data file. You must be sure to dimension the array so it will be large enough to store all your data variables. In this case, the array is dimensioned to ten since we'll only have ten variables. Line 30 is a programmed LOAD instruction which allows the INPUT statement in line 50 to accept inputs from the cassette. Lines 40-60 form a loop which reads the data file from the cassette and stores the data variables in array "D".

Line 70 stores a decimal 0 at decimal memory location 515. On the Challenger II this memory location is a flag which controls the system monitor's cassette load routine. A decimal 0 stored at the location exits the routine and a decimal 255 stored at the same location will enter the load routine. It is necessary to exit the load routine in this manner so that the program using the array variables will be executed directly, without the program stopping after the array is filled. If the program was stopped after the array had been filled to exit the load routine in the usual fashion (space bar, carriage return, etc.), it would be necessary to type RUN to restart the program. Each time you type RUN all variables are set to zero; this would include the array we just filled with data from the data file.

Lines 80-130 in Program 3 simply list the variables which were retrieved from the data file so you can see how this technique works.

In the actual use of Program 3, the program which will use the retrieved data would follow immediately after line 70.

```
10 REM WRITE DATA FILE TO CASSETTE FROM DATA STATEMENTS
20 INPUT ''SET UP AND START RECORDER...TYPE'1' TO RECORD DATA''; A
30 SAVE
40 FOR I = 1 TO 10
50 READ D
60 PRINT D
70 NEXT I
80 END
100 DATA 1,2,3,4,5
110 DATA 6,7,8,9,10
```

Listing 1

```
10 REM WRITE DATA FILE TO CASSETTE FROM AN ARRAY
20 INPUT ''HOW MANY FILES IN DATA FILE'';N
30 DIM D(N)
40 FOR I = 1 TO N
50 INPUT ''DATA''; D(I)
60 NEXT I
70 INPUT ''SET UP AND START RECORDER...TYPE '1' TO RECORD DATA'';A
80 SAVE
100 PRINT D(I)
110 NEXT I
120 END
```

Listing 2

```
10 REM RETRIEVE DATA FILE
20 DIM D(10)
30 LOAD
40 FOR I = 1 TO 10
50 INPUT D(I)
60 NEXT I
70 POKE 515,0 : REM EXIT MONITER CASSETTE LOAD ROUTINE
80 REM THE PROGRAM USING DATA ARRAY WOULD START HERE
90 REM PRINT OUT ARRAY FOR TEST OF TECHNIQUE
100 FOR I = 1 TO 10
110 PRINT D(I)
120 NEXT I
130 END
```

Listing 3

To demonstrate the retrieval of a data file, enter Program 3; place the tape with the data file you created with Program 1 into your recorder. Rewind the tape to the erased leader portion you created. Type RUN. The INPUT statement's question mark will appear to signify that the program is waiting for input from the cassette interface.

You can now start your recorder in it's playback mode, and upon the tape reaching the start of the data file the first data variable will appear following the question mark. Another question mark will appear followed by the second data variable and so on until all data has been retrieved.

When the last data variable has been retrieved, Program 3 will list the "D" array so you can see that the array now contains the data retrieved from the data file.

If you should discover that the first data variable is something other than what it should be, chances are that the leader before the data file had not been adequately erased or you may have started the tape playback somewhere other than in the erased leader portion of the tape.

To keep these programs short and simple, I used numerical data and a single one dimensional array. By modifying these programs using nested FOR-NEXT loops in place of the single loops, you can save and retrieve data in two dimensional arrays.

Data can also be saved and retrieved in several different arrays by using one or more FOR-NEXT loops, one for each array, one after another in each of the programs. It is also possible to save and retrieve string data files by using string variables in place of the numerical which were used in these simple programs.

I have obtained reliable results using these programs. Simple modifications such as I have mentioned have allowed me the pleasure of running some programs which I have previously been unable to run.

Hopefully I have provided you with a simple but useful technique to create and retrieve cassette data files with your Challenger II.

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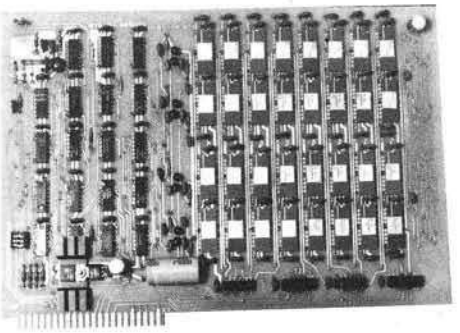

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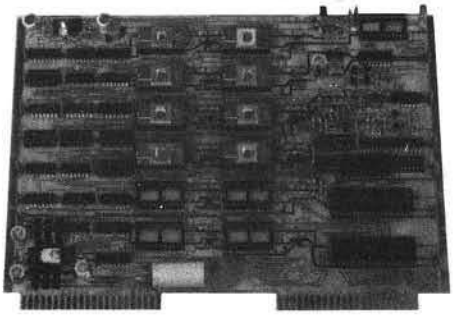

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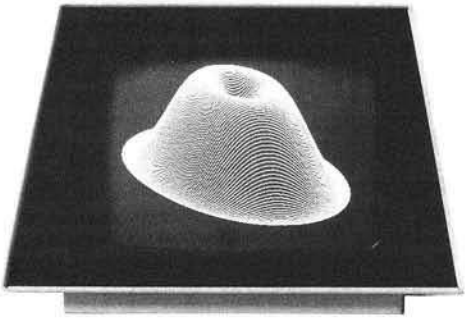

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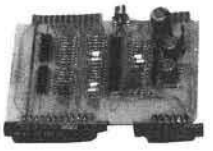

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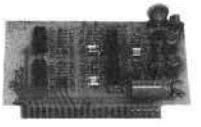

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Beginning Bolean: A Brief Introduction to Boolean Algebra for Computerists

It makes no difference if your computer is maxi or micro, if you program in machine code, BASIC or Pascal, if you do simple games or complex real-time simulations. In the final analysis: "It's All Ones and Zeros". How these ones and zeros are used is the topic of this primer.

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The School of the Ozarks
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Boolean algebra, invented by George Boole in the early 1800's, is useful in programming a microcomputer for logic design, designing interface circuits, and understanding the functions of integrated circuits. The last point is illustrated by opening the *TTL Data Book* and looking for logical expressions. For example, the 7453 is described by $Y = \overline{AB + CD + EF + GH + X}$ which has to be somewhat of a mystery without any Boolean background. The name tends to scare people, but it turns out that there is a very simple approach to learning Boolean algebra, namely Boolean arithmetic. Anyone who can accept that 1 + 1 = 1, can also learn Boolean. If you're an electrical engineer or a professional computer scientist, turn to the next article; otherwise give it a try.

Beginning Boolean

Boolean arithmetic is super-simple; there are only two numbers, zero and one. There are only two operations symbolized by + and ·.* Long division is out, and there is not a minus sign in sight. Figure 1 summarizes all you need to know about the + operation which is called "OR" rather than addition.

*The symbols ∨ and ∧ frequently replace + and ·, respectively. The dot (·) is sometimes implied, that is A·B = AB.

The OR facts are read "0 or 0 equals 0," *not* "0 plus 0 equals 0." Mumble these facts to yourself several times in the privacy of your own home. That will help you get a feeling for them. It is important to relate the OR operation with the circuit in Figure 1. A and B stand for switches. If switch A is closed then A = *1; if it is open then* A = 0. The same holds for switch B. Light L is off when L = 0 and it shines when L = 1. Referring to either the OR table or the OR facts in Figure 1, it is seen that if both switches are open we have 0 + 0 = 0 so the light is off. Likewise, the fact that 1 + 0 = 1 means that if switch A is closed, but B is open, then L = 1 so the light is on. This should also be obvious from the circuit. The last two OR facts are equally obvious to anyone who has played with switches and light bulbs. Slipping in a little algebra, unnoticed of course, the circuit is summarized by the simple equation:

$$A + B = L, \qquad (1)$$

which gives the correct value for L for each of the four possible combinations of switch settings. Go back and study the table and this paragraph again if you haven't understood.

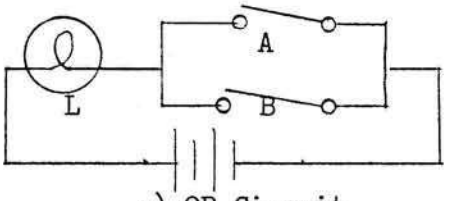
Before proceeding, a more conventional representation of the OR operation should be given, and surprisingly enough it appears in Figure 2. The information in Figure 2 is no different than in Figure 1, only the form has been changed. Actually the truth table has nothing to do with telling the truth or telling lies, but that's another story. Suffice it to say that somebody thought if everyone were

+	0	1
0	0	1
1	1	1

a) OR Table

0 + 0 = 0
1 + 0 = 1
0 + 1 = 1
1 + 1 = 1

b) OR Facts



c) OR Circuit

Figure 1: **Summary of the properties of the OR operation.**

logical we could sort truth from lies and the world would be a better place to live. Dream on!

If you will drop your conservative image for a moment, we might let A and B stand for a string of eight digits each instead of one digit each. Also, let the OR operation be applied to the digits of A and B in sequence. An example is shown in Figure 3. Hopefully you can reproduce this calculation in your own mind. Don't do anything heavy like "carry" or "borrow," just take two digits at a time, one from A and one from B, and apply the OR rule to them.

Since you are very likely the proud owner of an 8-bit computer, an examination of the instruction set will reveal an OR command which does what has just been described. The reader is left with a few problems. Assuming that you are familiar with representing 8-bit binary numbers with hexadecimal (hex) numbers, do the following OR problems. Answers to the first two are given.

11 + FE = FF	FF + 2B =
7F + 7F = 7F	00 + 3E =
22 + 01 =	FO + 5E =
3C + 00 =	FF + 00 =
12 + 34 =	

Having experienced the intellectual rewards of having mastered the OR operation, you will want to proceed to the AND operation.

AND Away We Go

Figure 4 summarizes the AND operation in the same fashion as Figure 1 treated the OR operation. The AND circuit is a series circuit, requiring that both A *and* B be on (hence the name) for the light L to light. This is in contrast to the OR circuit which lights if either A *or* B is on.

Notice that "ANDING" works the same way as old-fashioned multiplication with no weird results like 1 + 1 = 1 which we obtained with the OR. The AND facts are read "0 and 0 equals 0," or "1 and 1 equals 1." The equation which describes the circuit is:

$$A \cdot B = L, \qquad (2)$$

the truth of which may be verified by substitution and comparison with the simple series circuit. As before, a more conventional representation of the AND operation is given by a truth table and logic symbol shown in Figure 5.

As before, A and B may be taken to represent 8-bit numbers, and an example of such an AND operation is given in Figure 6. Your microprocessor's instruction set will include an AND command which takes two 8-bit words and ANDs them, as illustrated in Figure 6.

A	B	A+B
0	0	0
0	1	1
1	0	1
1	1	1

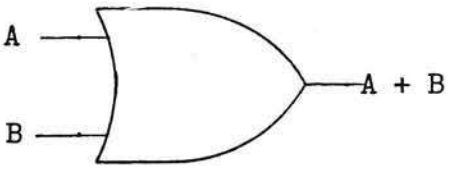


Figure 2: **Truth Table and logic symbol for the OR operation.**

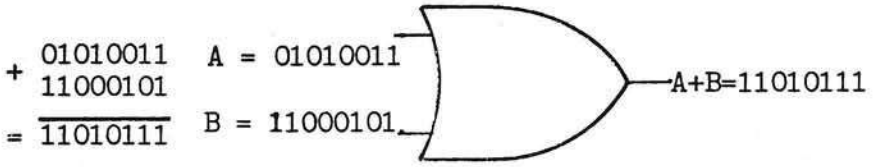


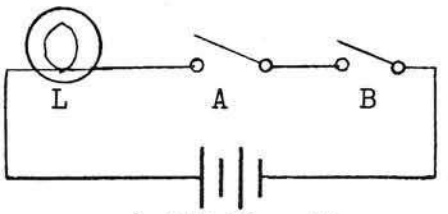
Figure 3: **Example of an 8-bit OR operation.**

•	0	1
0	0	0
1	0	1

a) AND Table

0 • 0 = 0
0 • 1 = 0
1 • 0 = 0
1 • 1 = 1

b) AND Facts



c) AND Circuit

Figure 4: **Summary of the properties of the AND operation.**

A	B	A•B
0	0	0
0	1	0
1	0	0
1	1	1

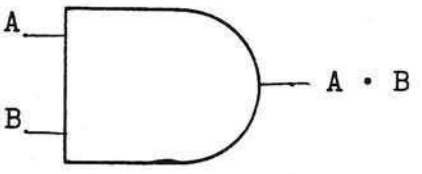


Figure 5: **Truth Table and logic symbol for the AND operation.**

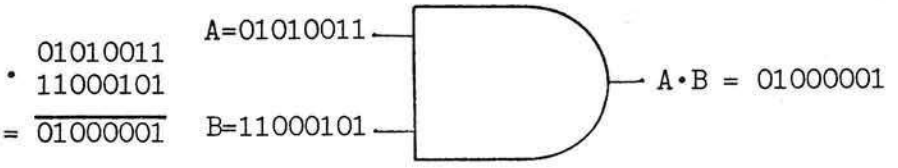


Figure 6: **Example of an 8-bit AND operation.**

Try the following AND problems where the 8-bit binary numbers have been represented in hex.

FF·11 = 11	33·BC =
7F·7F = 7F	00·3E =
OF·37 =	FO·37 =
80·FF =	80·11 =
55·40 =	

Everyone Loves a COMPLEMENT

There is another Boolean process called complementation or negation. It is a simple but very important idea. All complementation facts are summarized in Figure 7, using a truth table and the logic symbol. Clearly, complementation simply changes 0 to 1 and 1 to 0. The bar over the variable indicates complementation, and the inversion circle at the end of the triangle symbolizes complementation. A triangle without such a circle performs no inversion and in computer literature usually refers to a buffer. $\overline{A}$ is read as "not A."

It's Not a Complement to be Called EXCLUSIVE

There is another operation in Boolean mathematics which is the exclusive or, which for our purposes we shall call EOR, and we shall give it the symbol $\oplus$. I didn't really lie to you in the second paragraph when I said there were only two operations. It turns out that the EOR operation can be accomplished with ORs and ANDs, but it is somewhat simpler to think of it as a third operation. Figure 8 gives the truth table for EOR, the logic symbol, and an example of an 8-bit computation. Later we shall see how it can be implemented with ORs and ANDs. Try some of the problems given earlier for OR and AND operations only do EOR operations. For example, FF $\oplus$ 11 = EE and 7F$\oplus$ 7F = 00. Doing some EOR arithmetic may lead you to some interesting but important generalizations. In any case, in an EOR operation, if the digits are alike, the result is 0; but if the digits are different, the result is 1.

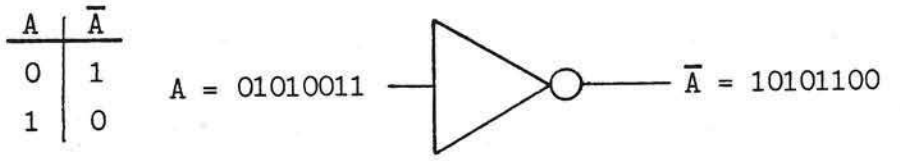


Figure 7: **Truth Table and logic symbol for complementation.**

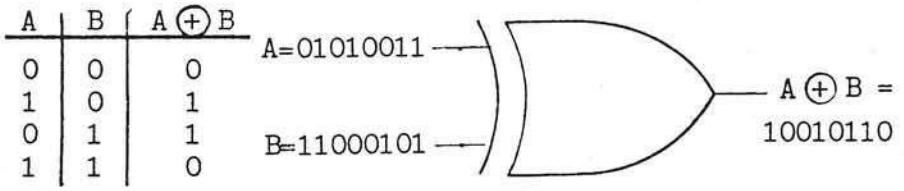


Figure 8: **Truth Table and logic symbol for EOR operation.**

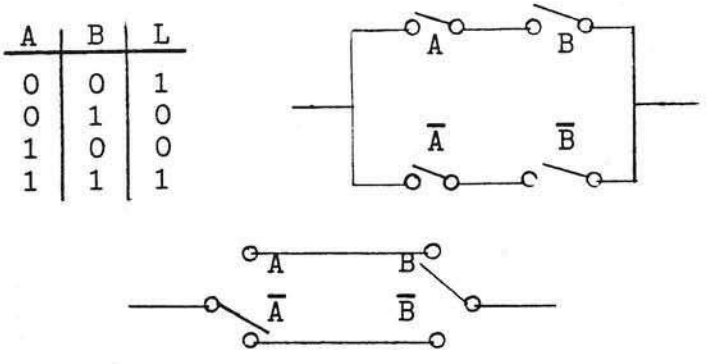


Figure 9: **Truth Table and circuit diagram for the coin matcher.**

If You're Exclusive You May Get A Complement

In checking over the instructions for my microprocessor, I find that no complementation command exists. Wow! Here is a fundamental Boolean concept which is missing. If you played with some EOR problems you may have already discovered how to produce a complement with the EOR operation. Suppose we deal with 1 digit numbers for the time being. Consider 1$\oplus$ A for a starting problem. Clearly if A is 1, 1$\oplus$ 1 = 0 which is the complement of A. On the other hand, if A is 0, then 1$\oplus$ 0 = 1, which is the complement of A. So both possibilities give the complement of A. Summarizing,

$$1 \oplus A = \overline{A} \quad (3)$$

If A is an 8-bit binary number represented by a hex number, equation (3) becomes FF$\oplus$ A = $\overline{A}$. In other words, if you want the complement of a number, do an exclusive or with it and a word containing all ones.

Designing Circuits — A Simple Application

You now know how to OR, EOR, AND and COMPLEMENT. You would like to know how to do something with what you have learned, right? Let's start with a simple problem; namely, constructing an electric coin flipping game. Actually, no coins will be flipped, but the principle is the same. Our machine will have two switches A and B. When the switches are the same a light will light, when they are different the light will be off. This, of course, corresponds to the case of both coins being the same (light on) or one coin coming up heads while the other comes up tails.

The first step in the design is to construct a truth table (sometimes called a closure table) for the system. We require that when A and B are both on the light is lit, when they are both off the light is lit, but when they have different settings (one on, the other off) the light is off. The truth table we would like to implement is clearly the one shown in Figure 9. This is constructed by first listing the four possible combinations for two switch settings, that is 00, 01, 10, and 11. For each of these switch settings the desired value of L is listed, completing the truth table. It is seen that when the switches "match" then L = 1, otherwise it is 0.

The next step in the design is to develop the Boolean equation which is equivalent to the truth table. This is accomplished by the following two steps:

1. Identify all rows with a 1 in the last column. AND the elements making up these rows, complementing those with a 0 in the row.

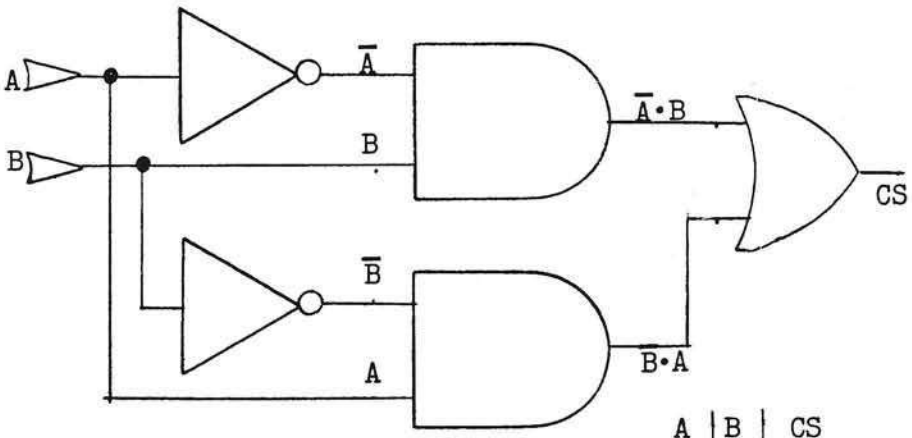
2. OR the products obtained in step 1 and set the result equal to the variable in the last column.

For the first step above and the truth table of Figure 9, we obtain the products $\overline{A}\cdot\overline{B}$ and $A\cdot B$ from the first row and the last row, respectively. Step two then gives the equation,

$$\overline{A}\cdot\overline{B} + A\cdot B = L, \quad (4)$$

which is the equation for the circuit. It is important for you to verify, by substituting in the various values of A and B given in Figure 9, that this equation does not in fact give the desired values of L.

The final step in the design is to construct a circuit which is equivalent to the equation (4). An examination of this equation indicates that we need two parallel branches, one containing $\overline{A}$ in the series with $\overline{B}$, the other containing A series with B. This circuit is shown in Figure 9. The battery and the light have been omitted for simplicity. Clearly the circuit could be constructed with two SPDT switches.



A	B	CS
0	0	0
0	1	1
1	0	1
0	0	0

Figure 10: **Truth Table and logic circuit for $A\cdot B + A\cdot B = CS$**

It is important to realize that the steps we took to design this particular circuit are perfectly general, that is, they are the same steps one would go through to design any logic circuit. Of course, with more switches the truth tables and the equations get more complicated. For example, with three switches our truth table would have 8 rows; four switches, 16 rows, and so on. Since this article is not meant to be an exhaustive (although you may feel that way) explanation of Boolean algebra, we will not proceed to more complex situations. For those you might want to pick up a textbook on digital electronics or computer science. But if you made it this far, you shouldn't have much trouble with the textbooks.

One other design study will illustrate several points. Suppose we require a logic 0 signal on a chip select pin when either of two other signals, call them A and B, are either both logic 0 or both logic 1. When A and B have opposite logic levels our chip select must be 1. This is clearly an artificial situation which originated in my mind and not in a computer interface circuit, but it illustrates a point. The truth table which fits the description demanded by the design is shown in Figure 10. Following the steps outlined earlier we find that the Boolean equation which implements the truth table is

$$\overline{A}\cdot B + A\cdot\overline{B} = CS. \quad (5)$$

An examination of the truth table will show that it is identical to the EOR table, and thus we have proved that EOR can be implemented with ORs and ANDs. A se cond point worth mentioning is that if A and B were single digit binary numbers, the value of CS is the value of the least significant digit in the binary sum of A and B. Thus equation (5) is also part of an adding circuit. If A and B are ANDED the correct value for the "carry" part of the binary addition is also produced. Together these circuits form what is a "half adder." Figure 10 also gives the logic symbol implementation of equation (5).

TO BE OR $\overline{\text{TO B}}$ = 1: Some Boolean Theorems

Once a truth table, closure table, or function table has been constructed for a particular design problem and the Boolean equation has been derived using the steps outlined in the previous section, then one usually tries to simplify the equation to minimize the number of integrated circuits which will be required for the circuit. Here is where Boolean algebra really becomes useful, for it is the theorems of Boolean algebra which allow complex looking equations and circuits to be simplified.

Because Boolean theorems are quite easy to understand and prove, and because they look different from the equations of real number algebra, a few of the simple theorems are listed in Table 1. An interesting property of Boolean algebra is illustrated by the first two columns. Note that column two can be obtained from column one by replacing all + signs with $\cdot$, if you replace all 1's with 0's.

It is quite easy and it is good practice to prove these theorems. They are proved by the method of exhaustion, namely all possible values for the variable are tried. For example, the first theorem can be proved by reasoning that A can be 1 or 0. If it is 1, then from the OR table $1+1=1$. If it is 0, then from the OR table $1+0=1$. So, for all possible values of A, $1+A=1$ and the theorem is proved. All the theorems in the first two columns may be proved in this manner. Theorems involving two variable A and B are usually proved using the four possible values for

$$1 + A = 1 \qquad 1\cdot A = A \qquad A + B = B + A$$
$$0 + A = A \qquad 0\cdot A = 0 \qquad \overline{A\cdot B} = \overline{B}\cdot\overline{A}$$
$$A + \overline{A} = A \qquad A\cdot\overline{A} = A \qquad \overline{A + B} = \overline{A}\cdot\overline{B}$$
$$A + \overline{A} = 1 \qquad A\cdot\overline{A} = 0 \qquad \overline{A\cdot B} = \overline{A} + \overline{B}$$

$$A\cdot B + A\cdot\overline{B} = A \qquad \overline{\overline{A}} = A$$
$$A + A\cdot B = A$$
$$A + (B\cdot C) = (A+B)\cdot(A+C)$$
$$A\cdot(B+C) = (A\cdot B)+(A\cdot C)$$

Table 1: **Some Basic Theorems from Boolean Algebra**

A and B, namely

$$A = 0011 = 03\text{Hex}$$

$$B = 0101 = 05\text{Hex}.$$

Theorems with three variables require 8 possible combinations to exhaust all the possible arrangements:

$$A = 10101010 = AAh$$

$$B = 11001100 = CCh$$

$$C = 11110000 = F\emptyset h$$

The purpose of expressing these in hex is so that you can try to prove the theorems on your computer, and at the same time get some experience in performing logical operations. All of the problems given earlier can also be solved on your computer. Theorems three and four in column three are the famous DE Morgan's theorems with which one can connect the ANDs and ORs with the NANDs and NORs of the real world.

To conclude, go back for a minute to that Boolean expression in the first paragraph. Suppose we ask what the value of Y will be if A and B are both 1. Using what you have just learned, the answer should be easy. If A and B are both 1 the AB (the dots are frequently omitted in AND operations) is 1. From the theorem in the first column of the theorem table it is clear that 1 OR anything is 1. Consequently, no matter what the other variables are, the value under the inversion or complementation bar is 1 if A and B are both 1. Inverting the 1 gives 0, so the answer is 0. Also if $X = 1$, then $Y = 0$, regardless of the states of the other variables.

I hope that you had some fun with this weird arithmetic. Perhaps your mind got bent out of shape as an added feature. But my main hope is that some of the mystery in those words "Boolean Algebra" has disappeared. I'll leave you with a homework problem. Draw the logic diagram to implement a full-adder, then expand it to handle 8-bit numbers. Finally, implement it with software on your 8-bit machine, and check your answer using the ADD instruction. Have some fun and get some books on digital electronics and/or computer science and dig into this stuff.

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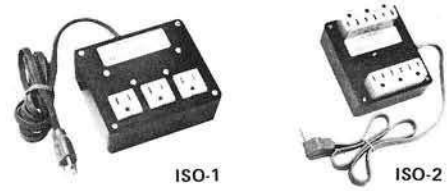

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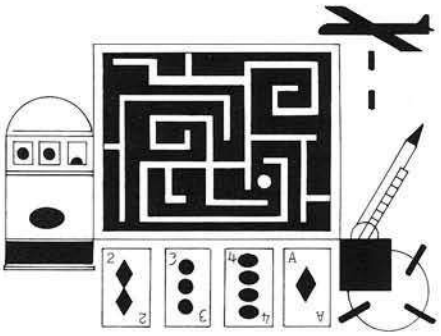

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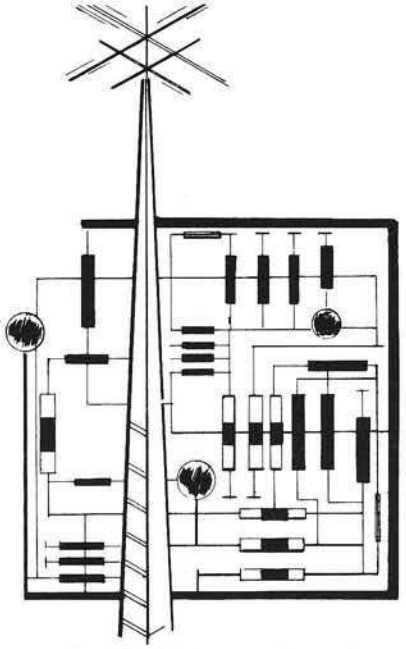

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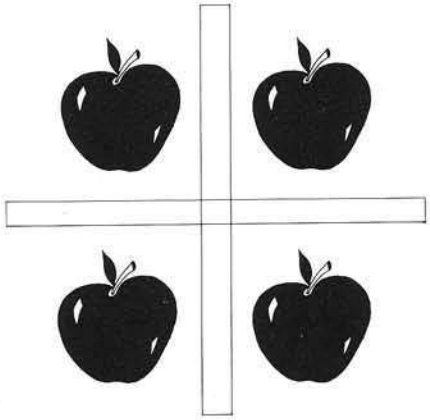

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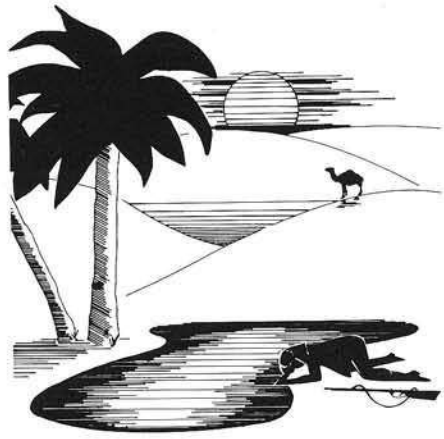

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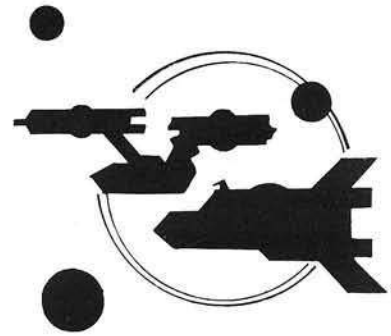

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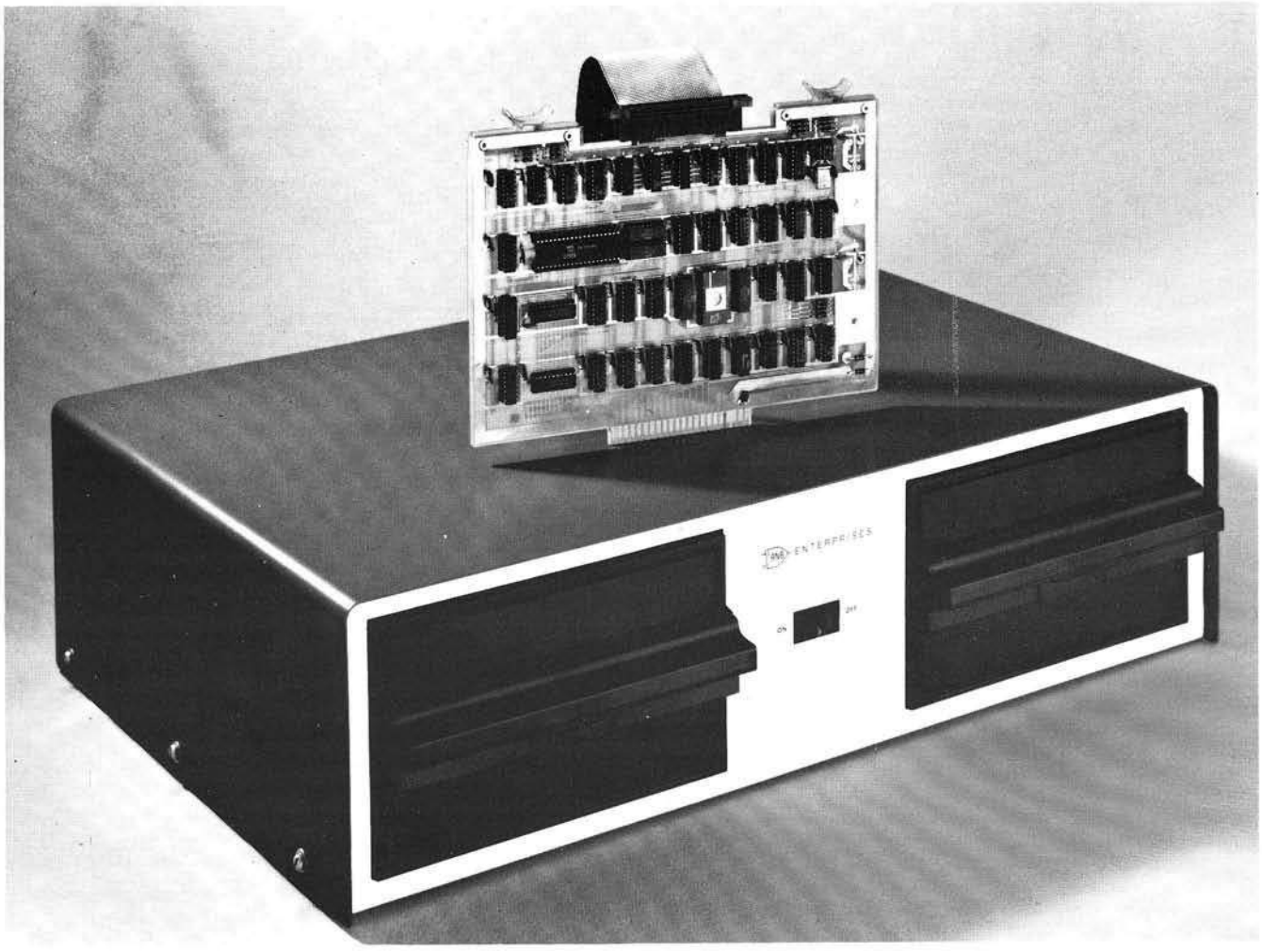

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Nicholas Vrtis
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I decided to write this program for selfish reasons. My hope is that everybody who transfers or writes programs for distribution will use it. The purpose of the program is to compute a sixteen bit checksum by adding up all the bytes in a program. This really isn't a totally new idea. Most methods of transferring programs or data external to a CPU use some sort of checksum routine. Even parity is really a one bit checksum. There is one major method of program transfer which makes almost no use of checksums. That method is listings published in magazines. One of the reasons is probably that noone has published a simple, general program to compute a checksum.

This program was written and tested on a SYM-1, but was designed to be as machine independent as possible. It should run on almost any 6502 system. There are only two monitor routines used, both of which are probably available in most monitors. The routine called OUTBYT outputs the contents of the 'A' register as two HEX digits. Just in case this routine isn't readily available on your system, I have also included a version of one at the end of the program. OUTCHR is a routine that outputs the contents of 'A' as a character; and unless your are using the HEX output routine, it is only used to output a space as a separator. The program does not assume that any registers are saved or restored by either monitor routine. It is completely relocatable (as is HEXOUT), and only uses four bytes of page zero memory. If you want to, you could even put it into an EPROM. The work area for the two byte checksum accumulator is obtained from the stack to avoid any more page zero requirements.

The theory and method of operation is simple. The starting address of the program to be summed is placed at locations $00 and $01 (low order first as usual). The ending address is placed at locations $02 and $03, and the program is started. The program will output an intermediate checksum after the end of each page of the summed program (i.e., each time the high order byte of the current address changes). This intermediate value would be useful in narrowing down the address of where a mistake lies. For a long program there might be a few of these intermediate sums; but then, that is also when they would be most helpful. Remember they still only narrow it down to 256 bytes (or less for the first and last values).

The program starts by zeroing the checksum accumulator by pushing two zero bytes onto the stack. The stack register then points to the next available stack location, which is actually $100 plus the stack register value in absolute address terms. The checksum accumulator is therefore at locations $101 and $102 plus the stack register value, since the stack register starts at $1FF and works toward $100 each time a value is pushed onto the stack. Transferring the stack register to the 'X' register lets us add directly to these two bytes. It would be possible to accomplish the same thing with Pulls and Pushes, but wouldn't have been as interesting. For the output of the last checksum value, the values are Pulled from the stack to keep the stack register the same before as after.

In addition to the aforementioned selfish motives, I have found the program to have other more mundane uses around the computer room. If you suspect a program is modifying itself (possibly by accident), compute the checksum before and after execution. If the checksums are the same, you can be reasonably confident that the program hasn't changed. I say reasonably confident because a simple checksum is not total proof that a program didn't change. If I add to one location and subtract the same amount from another, the checksum will still come out the same. It is orders of magnitude more accurate than guessing or eyeballing a memory dump though.

By the way, the checksum for this program ($04 to $48) is $1AAA! For the HEXOUT subroutine it is $08F8.

```
0010:
0020:                   SYM MONITOR ENTRY POINTS USED
0030: 0049              OUTBYT *     $82FA  OUTPUT °A° AS 2 HEX DIGITS
0040: 0049              OUTCHR *     $8A47  OUTPUT °A° AS ASCII
0050:
0060: 0000                     ORG   $0000
0070:
0080: 0000 00           STRTAD =     $00    PROGRAM STARTING ADDRESS LOW
0090: 0001 00                  =     $00    PROGRAM STARTING ADDRESS HIGH
0100: 0002 00           ENDAD  =     $00    PROGRAM ENDING ADDRESS LOW
0110: 0003 00                  =     $00    PROGRAM ENDING ADDRESS HIGH
0120:
0130: 0004 A9 00        PGMSUM LDAIM $00    ZERO CHECKSUM ON THE STACK
0140: 0006 48                  PHA
0150: 0007 48                  PHA
0160:
0170: 0008 BA           ADDIN  TSX          MOVE STACK POINTER TO INDEX
0180: 0009 A0 00               LDYIM $00    MAKE SURE Y REG IS ZERO
0190: 000B 18                  CLC
0200: 000C B1 00               LDAIY STRTAD GET A PROGRAM BYTE
0210: 000E 7D 02 01            ADCX  $0102  ADD TO CHECKSUM
0220: 0011 9D 02 01            STAX  $0102
0230: 0014 90 03               BCC   NOCARY
0240: 0016 FE 01 01            INCX  $0101
0250:
0260: 0019 E6 00        NOCARY INC   STRTAD ADVANCE TO NEXT PROGRAM BYTE
0270: 001B D0 15               BNE   CHKEND GO CHECK FOR END OF PROGRAM
0280: 001D E6 01               INC   STRTAD +01 OTHERWISE BUMP TO NEXT PAGE
0290: 001F BD 02 01            LDAX  $0102  OUTPUT INTERMEDIATE CHECKSUM ALSO
0300: 0022 48                  PHA          SAVE LOW ORDER ON STACK
0310: 0023 BD 01 01            LDAX  $0101  TO AVOID SAVING X
0320: 0026 20 FA 82            JSR   OUTBYT OUTPUT HIGH ORDER PART
0330: 0029 68                  PLA
0340: 002A 20 FA 82            JSR   OUTBYT THEN LOW ORDER
0350: 002D A9 20               LDAIM $20    SPACE
0360: 002F 20 47 8A            JSR   OUTCHR AND A SPACE AS SEPARATOR
0370:
0380: 0032 A5 01        CHKEND LDA   STRTAD +01 CHECK IF TO END OF PROGRAM
0390: 0034 C5 03               CMP   ENDAD  +01
0400: 0036 D0 04               BNE   CHKNDA
0410: 0038 A5 00               LDA   STRTAD
0420: 003A C5 02               CMP   ENDAD
0430: 003C 90 CA        CHKNDA BCC   ADDIN  LESS MEANS MORE TO GO
0440: 003E F0 C8               BEQ   ADDIN
0450:
0460: 0040 68                  PLA          ELSE GET HIGH ORDER OF CHECKSUM
0470: 0041 20 FA 82            JSR   OUTBYT ENO NEED TO PRESERVE THINGS
0480: 0044 68                  PLA
0490: 0045 20 FA 82            JSR   OUTBYT
0500: 0048 00                  BRK          CAUSE WE ARE DONE
0510:
ID=
HEXOUT    MICRO-WARE ASSEMBLER 65XX-1.0 PAGE 01


0010:
0020: 0200              HEXOUT ORG   $0200  RELOCATABLE
0030: 0200 48                  PHA          SAVE EXTRA COPY FOR SECOND HALF
0040: 0201 4A                  LSRA         SHIFT HIGH 4 BITS TO LOW ORDER
0050: 0202 4A                  LSRA
0060: 0203 4A                  LSRA
0070: 0204 4A                  LSRA
0080: 0205 C9 0A               CMPIM $0A    CHECK IF >9
0090: 0207 90 02               BCC   HEXOTA WILL SET CARRY IF >=
0100: 0209 69 06               ADCIM $06    PLUS 7 WILL OFFSET TO GET ASCII 'A'
0110: 020B 69 30        HEXOTA ADCIM $30
0120: 020D 20 47 8A            JSR   OUTCHR NOW OUTPUT THE FIRST HEX CHARACTER
0130: 0210 68                  PLA          GET ORIGINAL BACK
0140: 0211 29 0F               ANDIM $0F    ONLY WANT 4 LOW ORDER BITS NOW
0150: 0213 C9 0A               CMPIM $0A    SAME CONVERT TO ASCII
0160: 0215 90 02               BCC   HEXOTB
0170: 0217 69 06               ADCIM $06
0180: 0219 69 30        HEXOTB ADCIM $30
0190: 021B 4C 47 8A            JMP   OUTCHR LET THIS GUY DO THE RETURN
0200:
ID=
```

Classified Ads

SYM/KIM Appendix $4.25 postpaid, (see MICRO, 19:68 for description). First bk. of KIM: $10. Combo Appen. & 1st bk: $13.50. SYM-1 Hardware Theory Manual supplements, SYM-1 Ref. Manual $6.00. Order from:

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Sunnyvale, CA 94087

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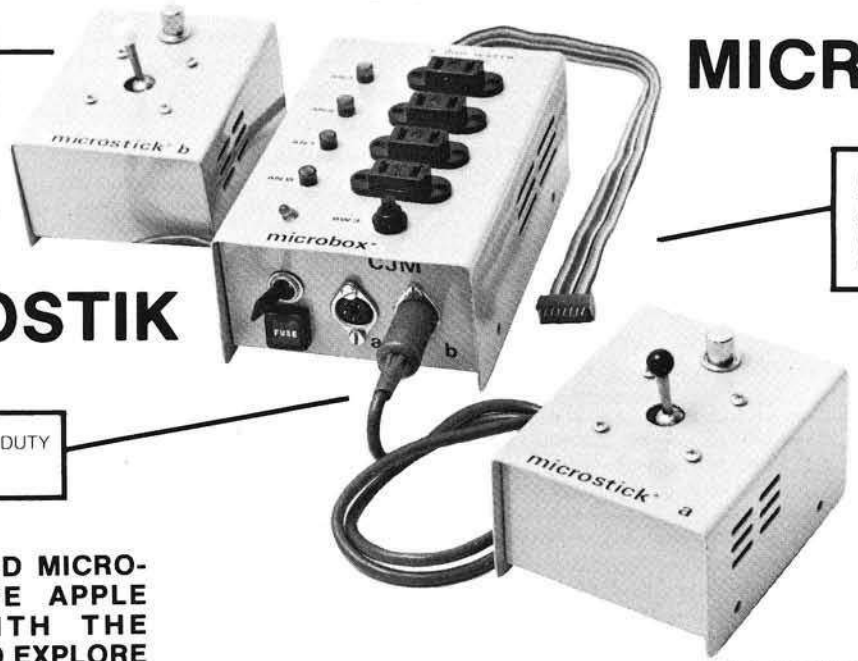

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Ask the Doctor

A technique to solve a problem in the AIM TTY service and a program for easy tape retrieval on the KIM are presented.

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The Serial TTY port on the AIM 65 works in a very similar fashion to that of the KIM described by Ben Doutre in MICRO issue number 12, May, 1979. The instructions for achieving synchronization at any baud rate (bits per second) are to switch the slide key from KB (keyboard) to TTY (Teletype), next press RESET and type DELETE on the teletype. The routine DETCPS measures the duration of the start bit and since the start bit is at logic level zero, then DELETE is a suitable character to use, because it consists of eight logic 1 signals following the start bit. Actually, about half of the characters on the keyboard would do just as well provided they *start* with a logic level 1 after the start bit. (Note the least significant bit is transmitted first.) The duration of the start bit is stored in CNTH 30 and CNTL 30 as explained previously.

An ordinary teletype works at 110 baud, but I have available a VDU which has a baud rate switch and will work at 110, 300, 600, 1200, 2400, 4800 baud. I tried all the rates with the AIM 65 hooked up and they worked perfectly, except for the 1200 baud. At this rate, no synchronization was achieved and only garbled rubbish appeared on the screen. This was of some concern to me because it was my intention to set up a three-way link between the VDU, the AIM 65 and a PRIME 400 computer and the PRIME was to operate *only* 1200 baud.

On pages 9-29 of the AIM 65 User's Guide the contents of CNTH 30 (at $A417) and CNTL 30 (at $A418) are listed for several baud rates. It is essential that the correct values can be entered by hand if synchronization does not work. The values quoted are only approximate, because the on-board crystal will not be exactly 4 M Hz and the devices linked up may vary slightly in baud rate. A check at the rates that did synchronize, showed some slight differences. Entering the values suggested for 1200 baud, namely, $02 for CNTH 30 (high byte) and $FD for CNTL 30 (low byte), produced perfect functioning of the VDU.

The Monitor Program Listing, page 10, shows that the programming between locations $E11B and $E144 times the start bit, using the timer T2 in the 6522 VIA dedicated to the monitor. The timer is started when the input goes low (start of bit) and when it goes high again (end of bit), the high byte count is read first and slightly later then the low byte count. The counter T2 counts downwards and the counters are initialized with $FF in both. The latch for T2 has $FF put into it permanently during initialization at reset, shown at program addresses $E067 to $E0D0. The value $FF is written into the high byte count at program address $E126, which also writes the latch value into the low byte count.

When the counter is read, the high and low bytes are complimented with $FF to get the duration of a bit in multiples of 1 mS. The counter start is delayed slightly by the time taken by the program instructions $E110 to $E126 and the low byte reading is delayed after the end of the start bit between instructions $E 129 and $E 136. Thus the count is too high and evidently requires reducing by 44 (decimal). This is carried out by the routine PATCH 1 at program address $FE 7C. If the low byte count happens to be less than 44 (it is, only for the 1200 baud rate), then the high byte count will require reducing by one also.

The carry bit is set correctly before the SBC instruction for 44. Unfortunately, the fault is that the carry bit is never examined to see if it is unset and then CNTH 30 reduced by one, either in the subroutine or back in the main program. Programming could be written by a user to overcome this problem, but it is not really worth the effort of loading. The simplest course is to attempt the synchronization, switch back to the AIM keyboard, then change $A417 from $03 to $02 using the M instruction. This gives the optimum count for the particular device connected to the serial interface.

On attempting the automatic synchronization at 1200 baud the values obtained for CNTH 30 and CNTL 30 were respectively $03 and $FO. The high byte value is different enough to cause the timing of each bit to be about 33 percent high, so the bits could not possibly be recognized by the VDU. I decided to investigate the reason for this, in case the VDU was faulty.

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Fast Tape Retrieval

Although I use the routine primarily for data retrieval for the TVT-6 video interface, it can readily be adapted for many other applications. Basically, it works as follows:

Press STart: Tape recorder starts and tape is read. When seven segment display reads 0000 A9, then

Fast Tape Retrieval

Although I use the routine primarily for data retrieval for the TVT-6 video interface, it can readily be adapted for many other applications. Basically, it works as follows:

Press STart: Tape recorder starts and tape is read. When seven segment display reads 0000 A9, then

Press GO: Tape recorder stops and the information from tape is displayed on a monitor. For next display file, again

Press STart, and so forth.

This provides a two button data retrieval system. The files on tape consist of ASCII data loaded into 0200 to 03FF. This, of course, can vary for other applications and could contain any type of data which would not interfere with the program located at the bottom of page zero. A small gap between files is convenient.

Hardware Interface: Consists of the relay circuit shown in figure 1. PB0 is used as the control port. The tape recorder must be set in the **PLAY** position.

Software Interface: Several items must be inserted memory in order to bring up the system. First, if used with the TVT-6, the SCAN program must be loaded beginning at 1780. Next, 17F9 must contain 00. This will allow continual reading of files without regard to ID numbers. Finally, the NMI vector must be entered:

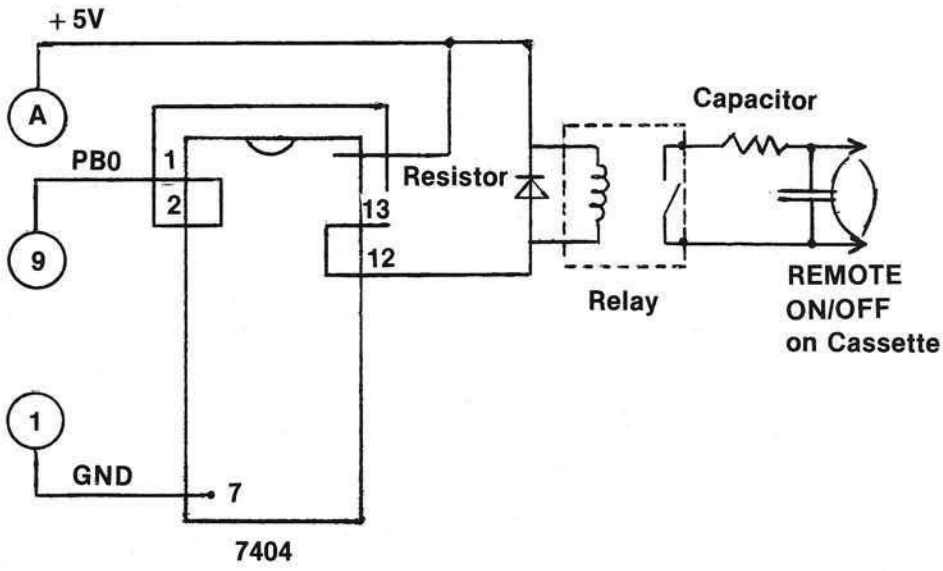
17FA 0B and **17FB 00**

The program utilizes the fact that on a proper tape read, the monitor returns at location 0000 XX. Now, 0000 is a memory location - a location which can be programmed like any other. I use this location to begin the tape/stop/display program. The **ST** button provides an **NMI** which points to the tape/start/read program.

```
0000 A9 01      GO      LDAIM $01     TURN TAPE OFF
0002 4D 03 17           EOR   $1703   BY TOGGLING CONTROL BIT
0005 8D 03 17           STA   $1703
0008 4C AD 17           JMP   SCAN    JUMP TO SOME PROGRAM

000B A9 01      ST      LDAIM $01     ST INTERRUPT
000D 4D 03 17           EOR   $1703   TURN TAPE ON
0010 8D 03 17           STA   $1703   BY TOGGLING CONTROL BIT
0013 4C 73 18           JMP   $1873   JUMP TO TAPE READ

17FA 0B                 =     $0B     POINT TO 000B
17FB 00                 =     $00     FOR ST KEY
```



Ronald Kushnier
3108 Addison Court
Cornwells Heights, PA 19020

ASK the DOCTOR is presented as an opportunity for you to get information about the AIM, SYM, or KIM out to your fellow computerists. If you have a major article, a good program, a discussion of various features, or whatever, that is long enough for an article, then by all means, submit it as an article and get paid! If, however, you have some short comments, ideas, facts, warnings, etc. that you feel others will be interested in, but which are too short for an entire article, then send them to: ASK the DOCTOR, P.O. Box 6502, Chelmsford, MA 01824. You will not get paid for these "tidbits", but you will get full credit for them.

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HERE'S WHAT ONE USER HAS TO SAY . . .

REPRINTED BY PERMISSION FROM THE 6502 USER NOTES - ISSUE NO. 14

PRODUCT REVIEW of the HDE DISC SYSTEM by the editor.

A number of you have asked for details about the HDE full size disc system.

The system is based around the SYKES 8" drive with the 6502 based intelligent controller.

This drive is soft sectored, IBM compatible, and single density which lets you store about a quarter megabyte of data on a disc.

The system software, called FODS (File Oriented Disc System), manages sequential files on the disc much the same way files are written on magnetic tape - one after another. When a file is deleted, from a sequentially managed file system, the space that the file occupied is not immediately reallocated, as in some disc operating systems. As it turns out, this can be an advantage as well as a disadvantage since deleted files on the FODS system can be recovered after the file has been deleted. (This has saved my sanity more than once!) Of course when you want to recover some of the disc space taken up by a number of these deleted files, you can simply re-pack or compress the disc and all the active files will be shifted down until there are no deleted files hanging around using up space.

FODS has this ability to repack a disc.

When saving and loading in FODS you work with named files, not track and sector data or I.D. bytes. This makes life a lot easier. I've seen some disc systems where you have to specify track and sector info and/or I.D. bytes. What a pain that can be!

If you just want to save a source file temporarily, you can do that on what's known as "scratch-pads". There are two of these on a disc, "scratch-pad A" and "scratch-pad B", each of these temporary disc files can hold up to 16K or if "B" is not used, "A" can hold one file up to 32K in length. The only files that can be temporarily saved on scratch pad are files that have been built using the system text editor.

Being a dyed in the wool assembly language programmer, I really appreciate the FODS text editor! This line oriented editor is upwards compatible with the MOS/ARESCO editor but includes about everything you could ask for in a line editor. There is a full and semi-automatic line numbering feature, lines can be edited while they are being entered or recalled and edited later, strings can be located and substituted, the line numbers can be resequenced, the file size can be found, the hex address of a line can be known and comments can be appended to an assembly file after it has been found correct. Oops! I forgot to say lines can also be moved around and deleted. This isn't the complete list of FODS editor commands, just the ones that immediately come to mind.

Another very powerful feature of the system is the ability to actually execute a file containing a string of commands. For example, the newsletter mailing list is now being stored on disc. When I want to make labels, I would normally have to load each letter file and run the labels printing program. But with FODS, I can build up a "JOB" file of commands and execute it.

The job file in turn calls each lettered label file in and runs the label printer automatically. The way computers are supposed to operate right?

Here's a listing of the job file I use to print mailing labels:

```
:LIS PRTLBL
0005 LOD A:RUN %LABEL:LOD B:JMP.E000:
LOD C:JMP.E000:
0010 LOD D:JMP.E000:LOD E:JMP.E000:
LOD F:JMP.E000:
0015 LOD G:JMP.E000:LOD H:JMP.E000:
LOD I:JMP.E000:
0020 LOD J:JMP.E000:LOD K:JMP .E000:
LOD L:JMP E000:
0025 LOD M:JMP E000:LOD MC: JMP.E000:
LOD N:JMP.E000:
0030 LOD O:JMP.E000:LOD P:JMP .E000:
LOD R:JMP.E000:
0035 LOD S:JMP.E000:LOD T:JMP .E000:
LOD V:JMP.E000:
0035 LOD S:JMP.E000:LOD T:JMP .E000:
LOD V:JMP.E000:
0040 LOD W:JMP.E000:LOD XYZ: JMP.E000:
0045 LOD EXCH:JMP.E000:LOD COMP:
JMP.E000:
```

Remember the MOS/ARESCO assembler I reviewed several issues ago? Well HDE went and fixed up all the problem areas that I mentioned in the review and then took it several steps further. The HDE assembler is an honest to goodness two-pass assembler which can assemble anywhere in memory using multiple source files from the disc. The assembler is an optional part of the system.

If you're the kind of person (as I am) who enjoys having the ability to customize, modify, and expand everything you own - you'll enjoy the system expansion abilities FODS has to offer. Adding a new command is as simple as writing the program, giving it a unique three letter name and saving it to disc. Whenever you type those three letters the system will first go through its own command table, see that its not there and then go out and read the disc directory to see if it can find it. If it's on the disc it will read it in and execute it. Simple right? I've added several commands to my system and REALLY appreciate having this ability. Some of the things I've added include a disassembler, an expanded version of XIM (the extended machine language monitor from Pyramid Data), Hypertape, and a number of system utilities which make life easier. By the way, to get back to the system, all you need to do is execute a BRK instruction.

HDE also provides a piece of software that lets you interface Microsoft 9 digit BASIC to their disc system. The software allows you to load the BASIC interpreter itself from disc as well as saving and loading BASIC Programs to and from the disc. This particular version of the software doesn't allow for saving BASIC data but HDE mentioned that this ability may be possible with a future version.

The first thing I do with a new piece of software after I get used to using it is try to blow it up. I did manage to find a weak spot or two in the very first version of FODS (a pre-release version) but the later, release version has been very tight.

The standard software that is included with the system consists of the disc driver software, the system text editor and the BASIC software interface. Several command extensions may also be included. All the necessary stuff like a power supply, the KIM-4 interface card, and all cables and connectors are included. It took me about 45 minutes to get things up and running the first time I put the system together.

Admittedly, a dual full size disc system from HDE is probably beyond the means of most hobbyists but if you or your company is looking for a dynamite 6502 development system, I would recommend this one. I've used the Rockwell System 65 while I was at MOS and feel that dollar for dollar, feature for feature, the HDE system comes out on top. The only place the HDE system falls short when stacked up next to the System 65 is in the area of packaging. At this point, there is no cabinet for the disc drives available from HDE.

So far, I've got nothing but good things to say about HDE and their products. Everything I've received from them has been industrial quality. That includes their documentation and product support. I'm very impressed with what I've seen from this company so far and quite enthusiastic over what my KIM has become since acquiring the disc system and its associated software.

ERIC

THANK YOU MR. REHNKE!

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Clocking KIM

While you probably are not going to use your $180 KIM to replace your $18 digital clock, a lot can be learned about proper use of the KIM and 6502 by building a clock as an exercise. This example includes use of the IRQ interrupt, driving the display, and calculating time. The program is intentionally NOT optimized, providing a challange for the reader.

Ronald A. Guest
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Denver,CO 80234

When I first laid eyes on KIM, something inside my head screamed out at me. It said, "That six digit display was just made to be a clock display." Not being the type of person who likes getting yelled at, I decided to look into the idea.

The idea may seem trivial or worthless, but the design of a clock program is both challenging and educational. When I first started this project I had only owned my KIM-1 slightly more than a month, and I had not made use of some of the KIM's features (such as the interval timer and interrupt capabilities). I had read the MOS Technology manuals carefully, but some things had to be learned the hard way -like the fact that decimal mode does not effect increments and decrements, PB7 of the 6530-03 must be wired to IRQ on the 6502 by the user, and how to use the KIM's displays. I learned through experience.

A clock program is not totally useless, either. Outside of being a good program for keeping the processor busy, it also could be valuable when run with other programs. If, for instance, you had your KIM connected to an A/D converter, the clock program would enable you to take readings at specified times during the day. Or, when you are going to be away from home, your microprocessor could turn lights, radios, etc. on and off as a deterrent to burglary. And, if you had to scrape together your last dollar to buy your KIM, and the old alarm clock just croaked, you can build an alarm to hang on your micro with parts from your tool box (see KIM-1 manual, page 57). You would then be the proud owner of the most intelligent alarm clock on the block.

A project such as this is an excellent way to become familiar with the features of your microprocessor. And, although there are several obstacles to be overcome, none are too difficult to surmount, given a little thought. The following discussion, intended for the KIM-1 could also serve as a guide for the development of a clock program on a similar system.

The first difficulty encountered in designing a clock program is a parallel processing problem: how to scan a display (or execute some other process) while at the same time, count the microseconds as they whiz by. Parallel processing on the KIM-1 can be achieved by the use of the 6502's interrupt capabilities. And since one of our processes is a simple counting mechanism, we can use the interval timer on the 6530-03 as our second "processor". The next two problems revolve around the interval timer.

The KIM's interval timer is only capable of timing intervals of 0.261102 seconds or less (with a 1MHz crystal). Problem number two results because of this. We need to simulate, through software, an interval timer able to time intervals of up to one second. This can be accomplished by writing a value(s) into the interval timer until a certain number of interrupts has occurred, and then updating the time. But, it is not quite that simple.

Which brings us to problem number three. We want to be as efficient as possible, which means we want to interrupt normal processing as little as possible. Thus, as large a value as possible should be written into the timer. The problem, the most difficult of all, is; what value(s) to write where, and how many times. The discussion must now become a little more detailed. Keeping efficiency in mind, we want to delay the maximum value between interrupts as many times as possible, without exceeding one second. This means that we should write a $FF into the ÷1024 location three times. This will give a delay of (3*255*1024)μs, or 0.216640 seconds less than one (1 – 0.783360).

As you can see, this value is less than the maximum interval. The largest value, less than 0.216640 seconds, that we can write to the interval timer is (211*1024)μs, or 0.216064 seconds. About now you are probably thinking, "Oh! Holy Bit Bucket, will this never end?" But don't fuse a power supply, this tedious process is coming to an end. Now, let's see. If we write a 9 into the ÷64 location, that will give us a delay of 576μs, and a grand total of exactly one second. Success! We have accomplished our task. But, wait. We've

got some software overhead to consider, right? Right. The software which simulates this interval timer, and the software which updates the time must be taken into consideration. The amount of time allocated to the execution of this software will vary slightly for different programs. But 32μs seems to be a sufficient amount of time. So we want our final delay to be 544μs (instead of 576). We can easily achieve this by writing 68 into the +8 location.

What do we have so far? We have three delays of (255*1024)μs, one delay for (211*1024)μs, and one delay of (68*8)μs; giving us a grand total of 999,968 μs. (Although not the only combination of intervals which yeild one second, this is the most efficient from the standpoint of the interrupted process.) Now, we need to take a look at the software necessary to simulate this timer.

The code needed to simulate a one second interval timer is given in listing 1. The first section of code gives us the delay of (3*255*1024), assuming that "NUMDLY" is initialized to one (1). The second group of instructions gives the delay of (211*1024), and the third group gives the delay of (68*8). To assure that your clock program will be accurate, you should determine how much time your software will actually require. When calculating the amount of software overhead for your particular program, remember that the execution time of instructions executed after the timer has been written into, should not be included. This is because the timer will have already started counting down, resulting in an overlap of the countdown and instruction executions. Taking Listing 1 as an example, and assuming "NUMDLY" is less than three (3), all instructions before "INCDLY" should be included, but the increment and restore instructions should not be, since they are executed after the timing begins.

The code in Listing 1 would be contained in an interrupt program, which consists of instructions to do the following;

1. save all registers on the stack,
2. determine if one second has elapsed,

   if not then (5), else,
3. add one second to the time,
4. reset "NUMDLY" and the timer, and,
5. restore the registers from the stack.

A block diagram of the process is given in Figure 1. The coding for the interrupt program occupies about 96 bytes of memory (most of it is used to update the time).

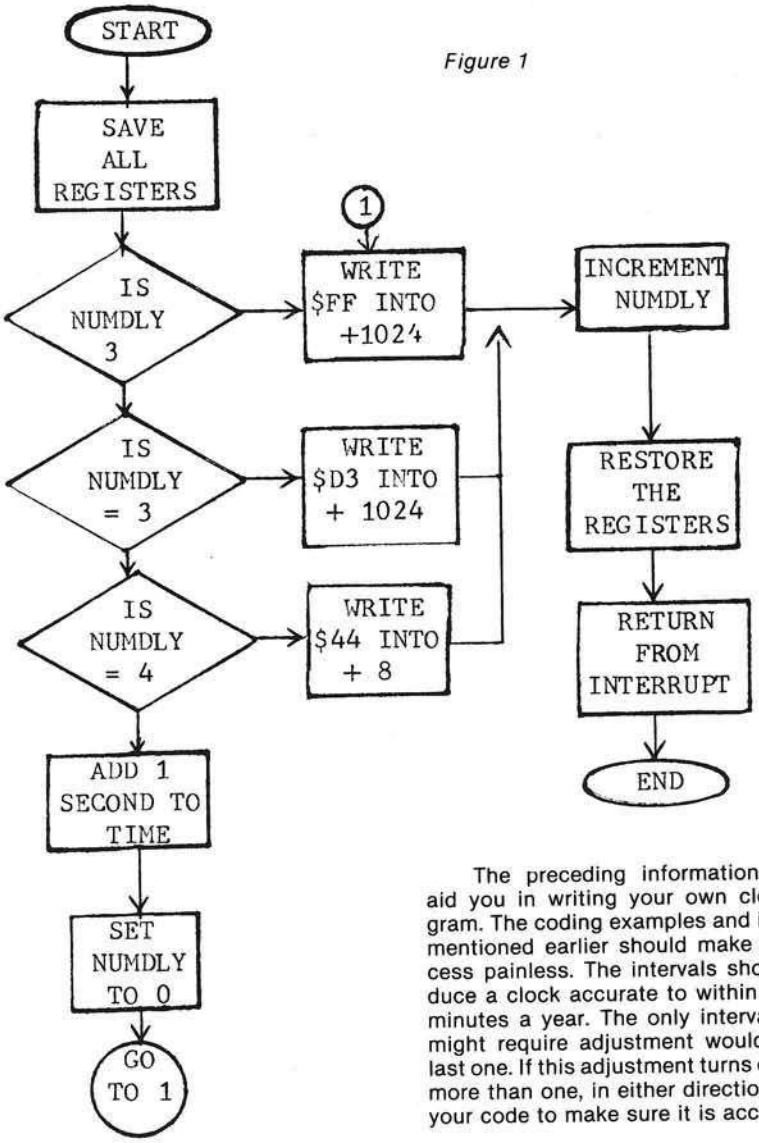

Figure 1

The updating code must:

1. add 1 to the seconds, if not 60 then (4), else zero seconds and
2. add 1 to the minutes, if not 60 then (4), else zero minutes and
3. add 1 to hour, if 13 (or 25 for a 24 hour clock) set hour to 1, else
4. continue.

Since time uses decimal digits, it is necessary to load the byte into the accumulator and perform an add; an increment would not be decimal. The code to update the seconds is given in Listing 2 as an example.

The preceding information should aid you in writing your own clock program. The coding examples and intervals mentioned earlier should make the process painless. The intervals should produce a clock accurate to within about 5 minutes a year. The only interval which might require adjustment would be the last one. If this adjustment turns out to be more than one, in either direction, check your code to make sure it is accurate.

Let me mention a few more things to help you avoid trouble. Don't forget that any program which is to run coincidentally with the clock program you must initialize the interval timer and counter (NUMDLY) at the outset. Also, after you have loaded the clock program into memory, you must also store the starting address of the program in the IRQ interrupt vector locations. And, last but not least, connect the PB7 pin of the 6530-03 to the IRQ pin of the 6502 (A-15 to E-4).

The clock program I have described contains the basic features of any digital clock. It could be expanded to keep track of the month, day, year, and/or just about anything else you could want. If you are willing to spend the time, the clock can be as accurate as the hardware will allow. Theoretically, my clock program should be accurate to within less than 2 minutes a year. In practice, I set the program by WWV and let it run for three days straight. At the end of this time, the seconds were

still clicking by, right on the nose. This should be enough accuracy for all but the most exacting and finicky of home-brewers. (I hope no one is going to run their clock program for a solid year.) Hopefully, the information information in this article, and the program itself, will be as useful to others as it has been to me. Good Luck!!

Listing 1

```
0010:                   INTERRUPT SERVICE ROUTINE TO RUN A REAL-TIME
0020:                    CLOCK ON A MOS TECHNOLOGY KIM-1.
0030:
0040:                   WRITTEN BY : RONALD A GUEST.
0050:
0060:                   COPYRIGHT 1976  BY  RONALN A. GUEST
0070:
0080: 0020                      ORG   $0020
0090:
0100: 0020              NUMDLY  *     $000D
0110: 0020              SECNDS  *     $000C
0120: 0020              MINUTS  *     $000B
0130: 0020              HOURS   *     $000A
0140:
0150: 0020 48                   PHA           SAVE REGISTERS ON STACK
0160: 0021 8A                   TXA             .
0170: 0022 48                   PHA             .
0180: 0023 98                   TYA             .
0190: 0024 48                   PHA             ..
0200:
0210:                        DELAY DETERMINED BY VALUE IN NUMDLY.
0220:                        IF DELAY IS < 3 THEN DELAY 255 * 1024
0230:
0240: 0025 A5 0D                LDA   NUMDLY
0250: 0027 C9 03                CMPIM $03
0260: 0029 10 0A                BPL   DELAYF
0270:
0280: 002B A9 FF        MAXDLY  LDAIM $FF
0290: 002D 8D 0F 17             STA   $170F
0300:
0310: 0030 E6 0D        INCDLY  INC   NUMDLY INCREMENT COUNT AND GO RESTORE
0320: 0032 4C 80 00             JMP   RESTOR    ..
0330:
0340:                        IF NUMDLY <> 3 BRANCH TO ONETST
0350:
0360: 0035 D0 08        DELAYF  BNE   ONETST
0370: 0037 A9 D3                LDAIM $D3     IF = 3 THEN DELAY 211*1024
0380: 0039 8D 0F 17             STA   $170F
0390: 003C 4C 30 00             JMP   INCDLY
0400:
0410:                        IF NUMDLY > 4 THEN ONE SECOND HAS ELAPSED
0420:
0430: 003F C9 04        ONETST  CMPIM $04
0440: 0041 D0 08                BNE   ONESEC
0450: 0043 A9 44                LDAIM $44     IF = 4 THEN DELAY 68*8
0460: 0045 8D 0D 17             STA   $170D
0470: 0048 4C 30 00             JMP   INCDLY
0480:
0490:                        ONE SECOND HAS ELAPSED, SO, INC STORED TIME
0500: 004B F8           ONESEC  SED           USE DECIMAL MATH.
0510: 004C A5 0C                LDA   SECNDS  SET SECONDS BYTE
0520: 004E 18                   CLC
0530: 004F 69 01                ADCIM $01     ADD DECIMAL 1.
0540: 0051 85 0C                STA   SECNDS
0550: 0053 C9 60                CMPIM $60     IF < 60 THEN FINISHED
0560: 0055 30 22                BMI   RESET
0570: 0057 A9 00                LDAIM $00     ZERO SECONDS
0580: 0059 85 0C                STA   SECNDS
0590:
0600:                        INCREMENT MINUTES
0610:
0620: 005B A5 0B                LDA   MINUTS GET MINUTES BYTE
0630: 005D 69 00                ADCIM $00     ADD IN CARRY FROM PREVIOUS COMPARE
0640: 005F 85 0B                STA   MINUTS
0650: 0061 EA                   NOP           FOR TIMING
```

```
0660: 0062 C9 60          CMPIM $60    IF < 60 , FINISHED
0670: 0064 30 13          BMI   RESET
0680: 0066 A9 00          LDAIM $00    ZERO MINUTES
0690: 0068 85 0B          STA   MINUTS
0700:
0710:                    INCREMENT HOURS
0720:
0730: 006A A5 0A          LDA   HOURS
0740: 006C 18             CLC          THIS TIME CLEAR CARRY (FOR TIMING)
0750: 006D 69 01          ADCIM $01
0760: 006F 85 0A          STA   HOURS
0770: 0071 C9 25          CMPIM $25    WOULD BE 13 FOR 12 HOUR CLOCK
0780: 0073 30 04          BMI   RESET
0790: 0075 A9 01          LDAIM $01
0800: 0077 85 0A          STA   HOURS
0810:
0820:                    RESET TIMER AND NUMDLY
0830:
0840: 0079 A9 00     RESET LDAIM $00
0850: 007B 85 0D          STA   NUMDLY
0860: 007D 4C 2B 00       JMP   MAXDLY
0870:
0880:                    RESTORE REGISTERS
0890:
0900: 0080 68        RESTOR PLA
0910: 0081 A8               TAY
0920: 0082 68               PLA
0930: 0083 AA               TAX
0940: 0084 68               PLA
0950: 0085 40               RTI
0960:

                         THIS PROGRAM DISPLAYS THE HOURS, MINUTES, AND SECONDS

0070: 0200                ORG   $0200
0080:
0090: 0200           NUMDLY *     $000D
0100: 0200           CONVD  *     $1F48
0110: 0200           TIME   *     $000A
0120:
0130: 0200 A9 01          LDAIM $01    INITALIZE INTERRUPT COUNTER
0140: 0202 85 0D          STA   NUMDLY
0150: 0204 A9 FF          LDAIM $FF    INITALIZE DIVIDE BY 1024 COUHTER
0160: 0206 8D 0F 17       STA   $170F
0170: 0209 58             CLI          ENABLE INTERRUPTS
0180: 020A A9 7F          LDAIM $7F    INITALIZE DISPLAY PORT
0190: 020C 8D 41 17       STA   $1741
0200: 020F A2 09     START LDXIM $09    X REG POINTS TO DIGIT TO BE DISPLAYED
0210: 0211 A0 00          LDYIM $00    Y REG IS INDEX TO TIME BYTE TO BE DISPLAYED
0220:
0230:                    THIS IS THE START OF THE LOOP
0240:                    THE PRECEEDING CODE IS INITALIZATION
0250:
0260: 0213 C0 04     LOOP  CPYIM $04    IF Y REG IS >= 4 THEN JUMP BACK TO START
0270: 0215 10 F8           BPL   START
0280:
0290: 0217 B9 0A 00        LDAY  TIME   GET BYTE OF TIME POINTED TO BY Y REG
0300: 021A 4A              LSRA         GET HIGH ORDER 4 BITS
0310: 021B 4A              LSRA
0320: 021C 4A              LSRA
0330: 021D 4A              LSRA
0340: 021E 20 48 1F        JSR   CONVD  OUTPUT 4 BITS TO POSITIONPOINTED
0350:                        TO BY X REG
0360: 0221 B9 0A 00        LDAY  TIME
0370: 0224 29 0F           ANDIM $0F    GET LOW ORDER 4 BITS
0380: 0226 20 48 1F        JSR   CONVD  OUTPUT
0390: 0229 A9 00           LDAIM $00    TURN OFF DISPLAY
0400: 022B 8D 40 17        STA   $1740
0410: 022E C8              INY          INCREMENT Y REG
0420:                        X REG IS INCREMENTED BY CONVD
0430: 022F 10 E2           BPL   LOOP   BRANCH ALWAYS TO LOOP
```

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A Home Message Center

If your house is like mine, there is never a pencil around when you need it, and when a message is left taped to the refrig, nobody ever notices. Put your messages on the APPLE and they will not be missed! This "Message Center" can be a starting point for other automatic display systems.

William McLean
1642 Edgewater Lane
Camarillo, CA 93010

This program was born from a dual need: I wanted to find a daytime use for my new computer, and I wanted to get my family involved in some small way with the APPLE so that they would lose that feeling of awe and "separation" that I see among the families of many computerists.

As I've had my APPLE for less than two months, the program would have to be fairly simple, but I really wanted to incorporate something creative. A tall order for a neophyte programmer who only learned the command LOAD two months ago, but I'm happy with the results and I hope that others will find some value in the ideas incorporated.

A few comments and explanations:

1. If you should happen to get an error message or hit control C, just type in GOTO 0 before listing so you'll have a full page to list without hitting reset.

2. Now you can type in GOTO 90 and the program should recommence without losing your message.

3. Temporary register K$ retains the last message even though it has been erased from the registers C$ through H$. So you can get it repeated by requesting it again even though the name no longer shows on the video screen.

4. This program has been set up to hold from 1 to 6 messages in a total of about 10K of RAM but can be modified to hold almost as mony more as you like if you have adaquate memory. You will need to modify number 90 to allow an extra line or two to display names (POKE 35,4 or 35,5); number 100 to move the display down an equal amount (POKE 34,4 or 34,5); line number 145 to check the extra registers for status; lines 150 through 160 to add more z "name strings"; 170 through 180 to add more "message strings"; and lines 190 through 200 tho erase the strings, once used.

The *Marquis* type of scrolling message is also useful for an nouncements for club meetings, o attention-getting continuous replay displays at shows or store windows. You can limit the number of times the message is displayed by deleting line 460 and assigning R in a 300 a value equal to the number of repeats that you want.

At home, we leave the video screen turned off and the APPLE II on. Each member of the family, upon seeing the computer "on" light, checks for messages by turning on the video momentarily and checking the names at the top of the screen.

One last hint: if you leave more than one message for the same person, you must change the "name" slightly. (I suggest a simple addition of a number, as in "John", "John2", "John3", etc.) If you should inadvertantly enter two messages for the same name, you will erase them both after only seeing one of them.

Copies of this program on cassette tapes are available from the author.

```
]PR#6
]PR#6

]LIST, PR#1
0  POKE 32,0: POKE 33,40: POKE 34
     ,0: POKE 35,24
20   DIM A$(255),B$(25),C$(25),D$(
     25),E$(25),F$(25),G$(25),H$(
     25)
21   DIM K$(255),CC$(255),DD$(255)
     ,EE$(255),FF$(255),GG$(255),
     HH$(255)
40 A = 0:C = 1
90   POKE 32,0: POKE 33,40: POKE 3
     4,0: POKE 35,3: HOME
95   INVERSE : PRINT "MESSAGES WAI
     TING FOR: ";: NORMAL : PRINT
     C$;D$;E$;F$;G$;H$
100  POKE 32,0: POKE 33,40: POKE
     34,3: POKE 35,24: HOME
120  HOME : PRINT "     =========
     ==========
        HOME MESSAGE CENTER
                    ============
     ======  "
121  PRINT : PRINT : PRINT
130  PRINT "WHICH DO YOU WANT ---
                          1.  ENTE
     R A NEW MESSAGE
         2.  RECEIVE A MESSAGE
                    ": INPUT "WHI
     CH?  ";X
131  IF X = 2 GOTO 185
140  INPUT "MESSAGE IS FOR (NAME)
       ";B$
141  IF  LEN (B$) > 1 THEN B$ = B
     $ + " - "
145  FLASH : IF  LEN (H$) > 1 AND
      LEN (G$) > 1 AND  LEN (F$) >
     1 AND  LEN (E$) > 1 AND  LEN
     (D$) > 1 AND  LEN (C$) > 1 THEN
      PRINT "SORRY, BUT ALL MY ME
     SSAGE REGISTERS ARE FULL!!":
      FOR Y = 1 TO 500: NEXT Y: GOTO
     90
146  NORMAL
150  IF  LEN (H$) < 1 AND  LEN (G
     $) > 1 AND  LEN (F$) > 1 AND
      LEN (E$) > 1 AND  LEN (D$) >
     1 AND  LEN (C$) > 1 THEN H$ =
     B$
152  IF  LEN (G$) < 1 AND  LEN (F
     $) > 1 AND  LEN (E$) > 1 AND
      LEN (D$) > 1 AND  LEN (C$) >
     1 THEN G$ = B$
154  IF  LEN (F$) < 1 AND  LEN (E
     $) > 1 AND  LEN (D$) > 1 AND
      LEN (C$) > 1 THEN F$ = B$
156  IF  LEN (E$) < 1 AND  LEN (D
     $) > 1 AND  LEN (C$) > 1 THEN
     E$ = B$
158  IF  LEN (D$) < 1 AND  LEN (C
     $) > 1 THEN D$ = B$
160  IF  LEN (C$) < 1 THEN C$ = B
     $
165  INPUT "THE MESSAGE IS?? (5 L
     INES OR LESS, IN   QUOTATION
      MARKS, PLEASE)
        ";A$
170  IF  LEN (HH$) < 1 AND  LEN (
     GG$) > 1 AND  LEN (FF$) > 1 AND
      LEN (EE$) > 1 AND  LEN (DD$
     ) > 1 AND  LEN (CC$) > 1 THEN
     HH$ = A$
172  IF  LEN (GG$) < 1 AND  LEN (
     FF$) > 1 AND  LEN (EE$) > 1 AND
      LEN (DD$) > 1 AND  LEN (CC$
     ) > 1 THEN GG$ = A$
174  IF  LEN (FF$) < 1 AND  LEN (
     EE$) > 1 AND  LEN (DD$) > 1 AND
      LEN (CC$) > 1 THEN FF$ = A$

176  IF  LEN (EE$) < 1 AND  LEN (
     DD$) > 1 AND  LEN (CC$) > 1 THEN
```

```
    EE$ = A$
178 IF  LEN (DD$) < 1 AND  LEN (
    CC$) > 1 THEN DD$ = A$
180 IF  LEN (CC$) < 1 THEN CC$ =
    A$
182 GOTO 90
185 INPUT "WHICH MESSAGE WOULD Y
    OU LIKE TO HAVE    DISPLAYED
    ?  (TYPE IN THE NAME EXACTLY
    )   ";J$:J$ = J$ + " - "
190 IF C$ = J$ THEN K$ = C$ + CC
    $: IF C$ = J$ THEN CC$ = "":
     IF C$ = J$ THEN C$ = ""
192 IF D$ = J$ THEN K$ = D$ + DD
    $: IF D$ = J$ THEN DD$ = "":
     IF D$ = J$ THEN D$ = ""
194 IF E$ = J$ THEN K$ = E$ + EE
    $: IF E$ = J$ THEN EE$ = "":
     IF E$ = J$ THEN E$ = ""
196 IF F$ = J$ THEN K$ = F$ + FF
    $: IF F$ = J$ THEN FF$ = "":
     IF F$ = J$ THEN F$ = ""
198 IF G$ = J$ THEN K$ = G$ + GG
    $: IF G$ = J$ THEN GG$ = "":
     IF G$ = J$ THEN G$ = ""
200 IF H$ = J$ THEN K$ = H$ + HH
    $: IF H$ = J$ THEN HH$ = "":
     IF H$ = J$ THEN H$ = ""
220 HOME : PRINT "     =========
    ==========
       HOME MESSAGE CENTER
                  ============
    ======  ": FOR X = 1 TO 9: PRINT
    : NEXT X
240 PRINT "TO ERASE CURRENT MESS
    AGE AND/OR TO      ENTER NEW
     MESSAGES, PUSH SPACE BAR"
260 FOR W = 1704 TO 1743: POKE W
    ,158: POKE W - 512,159: NEXT
    W
280 POKE 32,0: POKE 33,40: POKE
    34,11: POKE 35,13
300 FOR R = 1 TO 2: FOR M = 1 TO
    ( LEN (K$) + 40):A = M: IF A
     > 38 THEN A = 38
320 C = 1: IF M > 38 THEN C = M -
    37
340 REM   C=BEGINNING CHARACTER
    AND A=NUMBER OF EXTRA CHARAC
    TERS TO BE PRINTED.
360 HOME : HTAB 40 - A
380 PRINT  MID$ (K$,C,A): FOR X =
    1 TO 120: NEXT X
400 IF  PEEK ( - 16384) > 127 THEN
     GOTO 90
420 POKE  - 16368,0
440 NEXT M: NEXT R
460 GOTO 300
10000  REM  "HOME MESSAGE CENTER"
     WAS PROGRAMMED BY  BILL MCL
    EAN, 1642 EDGEWATER LANE, CA
    MARILLO, CALIF.  93010
10001  REM  ANYONE IS FREE TO USE
     AND COPY IT.  MY PHONE IS 8
    05-482-2048.  PLEASE CALL OR
     WRITE IF YOU COME UP WITH M
    EANINGFUL CHANGES.
?SYNTAX ERROR
```

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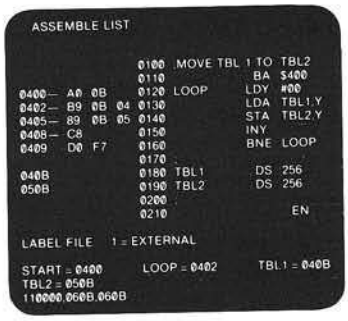

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Stop That PET!

That fantastic new program you are developing for the PET keeps bombing, causing the keyboard to lockup, and forcing you to RESET - thereby losing information about your program and its problems. Is there a way to STOP the run-away program? Would I ask the question if the answer wasn't "Yes"?

Gary J. Bullard
4808 S. Elwood 675
Tulsa, OK 74107

Commodore, for some reason, decided that the PET did not need a reset button. Since they did not provide a ROM monitor, perhaps they figured a reset button was unnecessary. This decision may have affected their sales somewhat.

They did provide a "STOP" button which serves as the equivalent of a CONTROL C, but this was useless if your cursor disappeared (a commom early PET problem) or your new machine-language program decided to loop forever instead of returning control to BASIC.

Machine-language programming for the PET therefore became an exercise in frustration:

1. Write your machine-language program.
2. Enter your program into the PET.
3. SAVE it. (Important!)
4. Execute your program via SYS or USR functions.
5. Stare impotently at dead PET. Frantically press STOP key as if you really think it will help.
6. Curse! Be creative!
7. Apply Commodore's RESET procedure. (i.e., turn PET off and back on)
8. Go back to step 2.

Somewhere between steps 2 and 3 you should perhaps examine your program for errors of coding or keypunching that could cause the PET to lock up. The difficulty with this procedure (for me anyway) is that if I thought the coding was wrong, I wouldn't have written it that way in the first place. So I'm left to examine five or six pages of coding that look perfectly good to me. What is needed is a way of knowing exactly where the program hung up so as to narrow the search.

If only there was a way to force an interrupt on the PET, then I could recover control and try again. At least it would eliminate steps 5, 6, 7, and 8. I could then insert breakpoints and narrow the problem down to a manageable level.

Commodore was ahead of me again.The non-maskable interrupt is permanently tied down so it vectors to the cold-start routines at power-on time. And since the cold-start routines destroy the contents of RAM, using this line as a reset would have the same effect as turning the PET off and on. I would have to make hardware changes and burn new PROMS to gain a reset capability with the non-maskable interrupt. Commodore wins this round.

But wait! Can Commodore be beaten at their own game? Maybe. . . .

There is one feature of the PET for which Commodore truly deserves a pat on the head . The PET has a built in real-time clock. This clock is updated by software once every sixtieth of a second. A circuit within the PET monitoring the AC line provides sixty interrupts a second. So the PET is not really "dead" at step 5 above. It is merrily executing your infinite loop and keeping good time, but it refuses to answer the keyboard; it is just playing dead.

Let's follow this idea a little way. Every sixtieth of a second, an interrupt is generated that causes the PET to jump indirectly through an address at $FFFE. This routine saves the accumulator, X register, and Y register on the stack and then jumps indirectly through $0219 to the clock routine. This vector is changed,when necessary, by the operating system to keep the clock routines from goofing up the timing for tape reads and writes. Normally, however, this vector remains constant. The exceptions to this rule will become important later.

Get the idea? Let's change that vector so the PET is forced to execute a short routine that checks the keyboard sixty times a second. Then, if the "STOP" key is pressed, we can provide a means of returning control to the operator. If the "STOP" key is not pressed, then the routine can proceed to its normal destination.

Now, since we've gone to this much trouble, why not see if we can derive some useful information from this exercise? It will be necessary to clean the stack so the BASIC warm-start address can replace the "real" interrupted return

address. Why not save this information so we can discover just where the interrupt occurred?

Those of you who have had the tenacity to read this far, but who are not the least interested in a desription of a machine-language program may wish to skip this section. How to use the program will be told in the last section.

Listing 1 is the "assembly" listing of my program. A few words would now be appropriate to describe my peculiar "assembler". This assembler is a one-line assembler, approximately equivalent to the assembler provided in the Apple II. However, it is written in BASIC, and it has a few features I find convenient. For instance, I think in decimal, so I like to know the decimal address of an instruction. This is handy, considering that the functions SYS, PEEK, and POKE all use decimal arguments. Therefore, I designed the format of the assembler to be: Decimal address, Hex address, Hex op code, Hex operands/addresses, Label (added later — this *is* a one line assembler), Mnemonic (extended mnemonic set, see below), Operand (decimal, ofcourse, or label added later), then Comments (also added later). Since my output device is an IBM selectric that is in no way connected to my PET, I take the liberty of dressing up my listings at my leisure.

Now, to the program.

Since our intention is to divert the interrupt vector to our own purposes, the routine at 8000 ($1F40) does just that. A SYS8000 done in immediate mode will cause the vector to be changed from its normal value to a value that will cause the PET to execute a routine located at 8016 ($1F50) every time an interrupt occurs. This same routine will reverse that vector. This way, you only need to remember one number to set or reset the vector. This routine works like this: the instruction SEI causes the interrupt disable flag to be set, preventing the cpu from recognizing any interrupts. This is done to prevent an interrupt from occuring while we are half through altering the vector. There is no telling where the thing would go if we don't take this precaution! The LDY VECTOR + 1 instruction gets a byte of the current vector so we can determine whether it is the normal or the altered vector. Then we JSR to the SET subroutine which sets the normal vector. If the vector was already set to normal, then we have wasted a few microseconds, but I can wait. Then we compare the Y register to see if the vector was normal. If Y equals 230 ($E6) then we JSR to the RESET subroutine and alter it. Else the BNE NOTSET causes execution to resume at 8014 ($1F4E), the CLI clears the interrupt flag, enabling interrupts once again, and exits via the RTS back to BASIC.

Now that we have altered the vector, the PET will execute the routine located at 8016 ($1F50) every time an interrupt occurs, which happens sixty times a second. Let's examine this routine.

First we jump to a subroutine located at 62250 ($F32A) which checks the keyboard and returns a zero in the accumulator if the STOP key is pressed. Upon return from that subroutine, we check the accumulator for zero, BEQ STOPPD. If the accumulator is zero, we jump to STOPPD, which is our recovery routine. If the accumulator is not zero we jump to CONINT, which is where the interrupt would normally have gone.

The instruction at 8024 ($1F58) loads 8 into the X register, then uses this as a counter and displacement to pull 8 bytes off the stack and store them in memory beginning at location 8165 ($1FE5). We pull 8 bytes off the stack instead of 6 because we assume at least one level of subroutine call beyond the interrupt. After all, we had to SYS or USR into our machine-language program, didn't we? We don't want the stack to get too cluttered. This isn't going to be a complete answer, but it will help. More will be said about this later.

Once we have stripped and saved the stack contents, we need to restore it. The routine beginning at 8033 ($1F61) does this. First, we load and stack the high byte and low bytes of the BASIC warm-start routine. Then we recall the original value of the status register and stack it. This is important only because of the interrupt flag. Then we stuff the stack with three bytes of anything just to fill it out. After all, the interrupt handling routine thinks it has stored the accumulator and the X and Y registers on the stack; it will expect them to be there. Since we are not returning to the place where the interrupt occurred, we don't care what those bytes are, so let's just push the status byte onto the stack three more times.

Now that we have cleaned the stack and provided for a fake return from the interrupt, how about displaying the information thus recovered? Sounds easy, yes? Not so.

If we are to display our hard-won information, we can either write our own display routines or use the routines so conveniently provided for in ROM. Being naturally lazy, I much prefer to use the routines already written. But this is a problem. When I first wrote this program I got strange results that I eventually traced to the fact that the interrupt flag was being cleared somewhere, permitting the routine to be interrupted if I don't remove my finger from the STOP button within one sixtieth of a second. I discovered that at location 58816 ($E5CO) in ROM there was a CLI instruction. Since this is the print routine, I needed to find a way to use it without allowing the interrupt to screw things up. It was necessary to exit from our routine, return to BASIC, and then display our information. How to do it? I chose to use a TRICK!! Follow closely...

The PET has a keyboard buffer that collects keystrokes until the operating system can service them. This gives the effect of the PET "remembering" keystrokes even if you enter them while your program is doing something other than looking for INPUTs or GETs. If you load this buffer while in a machine language program and then exit to BASIC, the PET will suddenly "see" a command in its keyboard buffer and proceed to execute it.

After we recreate the stack and set the normal interrupt vector (JSR SET) then we load the keyboard buffer with the command "SYS8066cr". The "cr" is a carriage return. The instruction at 8049 ($1F71) loads 9 into the X register. This number, which is the count for the buffer, is then stored in location 525 ($020D). Then the command is retrieved byte by byte from location 8128 ($1FCO) and placed in the keyboard buffer. When that is finished, the PET jumps to CONINT, the normal interrupt routine.

What follows is this: the PET updates the clock register, then jumps to the interrupt routine which restores the registers and "returns" to the BASIC warm-start routine. The prompt "READY." is printed, and control returns to BASIC. BASIC checks the keyboard buffer, sees the command "SYS8066", prints it and executes it. Control is now given to our display routine. Roundabout way of doing it, no?

The display routine begins at location 8066 ($1F82). First we load the accumulator and Y register with the address of our header line. Then we JSR to the print routine in ROM at 51751 ($CA27). After that we load the accumulator and X register with the bytes we stored that represent the interrupted return address, and JSR to the number display routine in ROM at 56479 ($DC9F). This routine displays numbers in decimal, so if you wish them displayed in hex you will have to convert them yourself. Next, a loop is set up that retrieves each byte and displays them — first the status byte, then the accumulator, and the X and Y registers — all in decimal. At the end of all this wonderful activity, the routine exits through the START which alters the interrupt vector so we can do the whole thing over again.

Now, aren't you sorry you decided to read this?

How to Load and Use This Program

Listing 1 is an assembly listing of this program. It may be of interest to people who enjoy machine-language programming, or those who like convoluted logic. It is difficult to enter machine-language programs into the PET, however. So I have provided listing 2, which is a BASIC version of this program. I have converted the machine-language program into DATA statements and built a small loader routine around them to make it easier to key into the PET and SAVE onto tape.

For those of you with the fortitude to attempt to enter this program into your PET, attend: First, this program will not work if your PET is one of the newer models. If your PET comes awake with ### COMMODORE BASIC ### instead of *** COMMODORE BASIC ***, then forget this program. Rumor has it that you don't need it anyway. Second, if you still qualify, notice that each DATA statement has exactly eight numbers. If you key this program in exactly as shown it will be easier to find errors later if you miss-key a number.

OK. Are you still with me? Then key the program into your PET exactly as shown but do not RUN!! When finished, SAVE the program on tape. Then replace line 36 with:

```
36 FOR X=8000 TO 8159: READ A:
P=P+X*A:NEXT X:PRINT P
```

Now RUN the program. If the number printed is 146725222, then the odds are very good that you made no mistakes. You may now LOAD and RUN the original program. If, on the other hand, your number did not match the above number, then recheck your keypunching, correct your error, and try again.

NOTE: I would like to take this opportunity to encourage all programmers who write programs involving many DATA statements to include a verify routine. It need not be a permanent part of the program, but should be designed to give the hobbyist some solid evidence that his efforts were accurate.

Now you have LOADed and RUN the program. Notice that line 15 protects the last page of an 8K PET from interference by BASIC. This routine will reside safely here while you write your new machine-language program, debug it, and test it. I put this program in high memory because it is a machine-language debugging aid and most machine-language routines for the PET are located in the second cassette tape buffer area 826-1023 ($033A-$03FF) for convenience. If you wish to relocate it, be very sure you understand how it works.

Notice we have not yet activated this routine. First LOAD your machine-language program if you have it on tape, or your assembler if you are just starting. Then execute a SYS8000. This activates the Reset routine. From now on, whenever you hit the STOP key, the machine will halt and display the address where it was interrupted plus the register contents. There are a couple of exceptions which will be noted below.

OK. The Reset routine is activated, you have entered your machine-language program into the second cassette buffer, and executed a SYS826. Somehow the expected results do not materialize and the new program does not return control to BASIC. Now what? Hit the STOP key! Suddenly the PET comes back to life and prints:

```
ADDR ST AC XR YR

835 34 129 66 202
```

Eureka! Somewhere around location 835 there was an error in your program. The status register contained 34, the accumulator had 129 in it, the X register had 66 and the Y register was holding a 202. Were they supposed to have these values? Perhaps a register was initialized wrong or a relative branch was figured wrong. At least you know where to begin looking. Isn't it wonderful?

If the STOP key is pressed during normal command mode, you will likely get:

```
ADDR ST AC XR YR

58013 34 0 1 3

READY.
```

Notice that the numbers do not align perfectly under the header. They are printed without regard to the size of the number but are printed in the order depicted by the header, separated by blanks. Also, while it happens too fast to see, what actually printed was:

```
READY.
SYS8066
  ADDR ST AC XR YR
  58013 34 0 1 3
READY.
```

The SYS8066 and the header are both prefaced with an up-cursor character, so that they are printed on top of each other. This makes less scrolling, in case the screen contents were important.

Now for the exceptions to the rules. Since it is impossible to know how deeply nested in subroutines the PET was when the interrupt occurred we cannot properly clean the stack. After a while (approximately 23 times) pressing the STOP key will cause a ?OUT OF MEMORY ERROR remark to appear. The Reset routine will be deactivated and it will be necessary to SYS8000 again. Nothing to worry about; the PET corrected the stack before it printed the error message. Another message that will deactivate the Reset routine is ?ILLEGAL QUANTITY ERROR. Same response: SYS8000.

The command SYS8000 will activate the Reset routine if it was not already activated. If the Reset routine is active, SYS8000 will turn it off. Be sure it is on when you are executing your new machine-language program. And be sure it is off whenever you want to use the tape recorder to LOAD or SAVE a program or read or write data files. The cassette routines will not work if the interrupt vector has been altered. If in doubt as to the current status of the Reset routine, simply hit the STOP key. If nothing happens, the routine is off. If you get a register display, the routine is on.

One final exception to the rule. This routine is excellent if you get caught in an infinite loop or you just want to exit from a machine-language program early. It won't protect you from all invalid op codes. Some invalid op codes act like NOPs or do some mysterious, undefined function. These are OK. There are some op codes, however, that will cause the PET to lock up in spite of our marvelous Reset routine. Hex 04 will do this for example. I suspect that these obstinate op codes do something to affect the interrupt flag, thus disabling our routine. Until Commodore see fit to provide a non-maskable interrupt, I guess we will have to live with this incovenience. But even so, it gives us a place to start looking, doesn't it? If your PET locks up in spite of the Reset routine, look for invalid op codes.

There you are. I hope this encourages more machine-language programming for the PET. Let's get full power out of our computers!

For your free information regarding the extended mnemonic set that was referenced above, send a self-addressed and stamped envelope to:

MICRO
P.O. Box 6502
Chelmsford, MA 01824

```
 DEC  HEX #1 #2 #3 LABEL  MNEM   OPER            COMMENTS

8000 1F40 78       START  SEI                    :Disable interrupts
8001 1F41 AC 1A 02        LDY    VECTOR+1        :Get interrupt vector Hi byte
8004 1F44 20 AE 1F        JSR    SET             :Set normal vector
8007 1F47 C0 E6           CPYIM  230             :Was normal vector already set?
8009 1F49 D0 03           BNE    NOTSET          :
8011 1F4B 20 B9 1F        JSR    RESET           :No - alter vector to CKSTOP routine
8014 1F4E 58       NOTSET CLI                    :Enable interrupts
8015 1F4F 60              RTS                    :Return to BASIC

           Check if STOP key pressed

8016 1F50 20 2A F3 CKSTOP JSR    STOP            :Check if STOP key pressed
8019 1F53 F0 03           BEQ    STOPPD          :Skip next instruction if STOPped
8021 1F55 4C 85 E6        JMP    CONINT          : Else continue normal interrupt
8024 1F58 A2 08    STOPPD LDXIM  8               :Set strip counter
8026 1F5A 68       SAVEM  PLA                    :Strip stack
8027 1F5B 9D E4 1F        STAX   STK-1           :Save bytes in memory
8030 1F5E CA              DEX                    :Reduce counter
8031 1F5F D0 F9           BNE    SAVEM           :Continue until 8 bytes removed

           Recreate the stack

8033 1F61 A9 C3    RESTK  LDAIM  195             :BASIC warm start Hi byte
8035 1F63 48              PHA                    :Stack it
8036 1F64 A9 8B           LDAIM  139             :BASIC warm start Lo byte
8038 1F66 48              PHA                    :Stack it
8039 1F67 AD E9 1F        LDA    STATUS          :Get real status byte
8042 1F6A 48              PHA                    :Stack it
8043 1F6B 48              PHA                    :Pad stack
8044 1F6C 48              PHA                    :   with dummy
8045 1F6D 48              PHA                    :      bytes
8046 1F6E 20 AE 1F        JSR    SET             :Set normal interrupt vector

           Create re-entry from BASIC warm start

8049 1F71 A2 09           LDXIM  9               :Get character count
8051 1F73 8E 0D 02        STX    KNT             :Store in keyboard buffer counter
8054 1F76 BD BF 1F SETSYS LDAX   SYS66-1         :Retrieve instruction
8057 1F79 9D 0E 02        STAX   KBUF-1          :Store in keyboard buffer
8060 1F7C CA              DEX                    :Reduce counter
8061 1F7D D0 F7           BNE    SETSYS          :Continue until done
8063 1F7F 4C 85 E6        JMP    CONINT          :Exit to normal interrupt routine

8066 1F82 A0 1F    DISPLY LDYIM  31              :Header Hi byte
8068 1F84 A9 CA           LDAIM  202             :Header Lo byte
8070 1F86 20 27 CA        JSR    ASPR            :Print header
8073 1F89 AD E7 1F        LDA    LOC             :Interrupted location Hi byte
8076 1F8C AE E8 1F        LDX    LOC+1           :Interrupted location Lo byte
8079 1F8F 20 9F DC        JSR    DCPR            :Print interrupted location
8082 1F92 A0 00           LDYIM  0               :Set and
8084 1F94 8C ED 1F        STY    CNTR            :  store counter
8087 1F97 AC ED 1F ALLREG LDY    CNTR            :Get count
8090 1F9A C0 04           CPYIM  4               :Have all been displayed?
8092 1F9C F0 A2           BEQ    START           :If so, reset vector, exit
8094 1F9E BE E9 1F        LDXY   STATUS          :Get next byte
8097 1FA1 A9 00           LDAIM  0               :Hi byte = zero
8099 1FA3 20 9F DC        JSR    DCPR            :Display byte
8102 1FA6 EE ED 1F        INC    CNTR            :Increment counter
8105 1FA9 4C 97 1F        JMP    ALLREG          :Continue until done

8108 1FAC EA              NOP                    :
8109 1FAD EA              NOP                    :

           SET and RESET subroutines

8110 1FAE A9 E6    SET    LDAIM  230             :Normal vector Hi byte
8112 1FB0 A2 85           LDXIM  133             :Normal vector Lo byte
8114 1FB2 8D 1A 02 SAVIT  STA    VECTOR+1        :Store Hi
8117 1FB5 8E 19 02        STX    VECTOR          :Store Lo
8120 1FB8 60              RTS                    :Return
8121 1FB9 A9 1F    RESET  LDAIM  31              :New vector Hi byte
8123 1FBB A2 50           LDXIM  80              :New vector Lo byte
8125 1FBD 4C B2 1F        JMP    SAVIT           :Store & exit

           SYS8066 constants

8128 1FC0 91       SYS66  DC     145             :Up cursor
8129 1FC1 53              DC     83              :    S
8130 1FC2 59              DC     89              :    Y
8131 1FC3 53              DC     83              :    S
8132 1FC4 38              DC     56              :    8
8133 1FC5 30              DC     48              :    0
8134 1FC6 36              DC     54              :    6
8135 1FC7 36              DC     54              :    6
8136 1FC8 0D              DC     13              :Carriage return

8137 1FC9 EA              NOP                    :

 DEC  HEX #1 #2 #3 LABEL  MNEM   OPER            COMMENTS

           Header constants

8138 1FCA 91       HEADER DC     145             :Up cursor
8139 1FCB 20              DC     32              :Space
8140 1FCC 41              DC     65              :    A
8141 1FCD 44              DC     68              :    D
8142 1FCE 44              DC     68              :    D
8143 1FCF 52              DC     82              :    R
8144 1FD0 20              DC     32              :Space
8145 1FD1 53              DC     83              :    S
8146 1FD2 54              DC     84              :    T
8147 1FD3 20              DC     32              :Space
8148 1FD4 41              DC     65              :    A
8149 1FD5 43              DC     67              :    C
8150 1FD6 20              DC     32              :Space
8151 1FD7 58              DC     88              :    X
8152 1FD8 52              DC     82              :    R
8153 1FD9 20              DC     32              :Space
8154 1FDA 59              DC     89              :    Y
8155 1FDB 52              DC     82              :    R
8156 1FDC 0D              DC     13              :Carriage return
8157 1FDD 00              DC     0               :End of message character
```

.....

```
                Working storage -- need not be initialized

8165 1FE5 00        STK     DC      0           :Extra Hi byte
8166 1FE6 00                DC      0           :Extra Lo byte
8167 1FE7 00        LOC     DC      0           :Interrupted Hi byte
8168 1FE8 00                DC      0           :Interrupted Lo byte
8169 1FE9 00        STATUS  DC      0           :Status byte
8170 1FEA 00                DC      0           :Accumulator
8171 1FEB 00                DC      0           :X register
8172 1FEC 00                DC      0           :Y register

8173 1FED 00        CNTR    DC      0           :Loop counter
```

Memory locations and ROM routines used

LABEL	DECIMAL	HEX	COMMENT
VECTOR	537	0219	Interrupt vector
KNT	525	020D	Keystroke counter
KBUF	527-536	020F-0218	Keyboard buffer
BASIC	50059	C38B	BASIC warm start
ASPR	51751	CA27	Print ASCII string terminated with a zero. Enter with ADH in Y, and ADL in A.
DCPR	56479	DC9F	Print the decimal integer whose binary value is in A (weight=256) and X (weight=1).
CONINT	59013	E685	Normal interrupt routine.
STOP	62250	F32A	Check to see if STOP key pressed. Returns a zero in accumulator if key is pressed.

```
 1 REM"■■■
```

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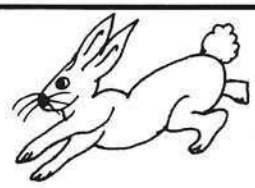

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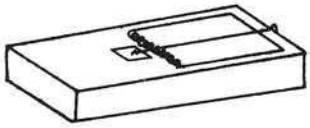

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The MICRO Software Catalogue: XVIII

Mike Rowe
P.O. Box 6502
Chelmsford, MA 01824

Name: **APPLESOFT-PLUS (APLUS) Structured Basic**
Memory: **16K (min.)**
Language: **6502 Assembly Language**
Hardware: **Standard (Disk, Autostart, and APPLESOFT ROM optional)**

Description: You don't have to buy APPLE PASCAL to begin enjoying the benefits of structured programming. APPLESOFT PLUS (APLUS), a 4K assembly-language program, is now available to add the following structured-programming commands to APPLESOFT Basic: When..Else..Fin, Until, While, (multi-line) If..Fin, Unless, Case, Select (variable), (Otherwise), 'DO (named procedure)', and 'TO (define a named procedure). The APLUS '&CONVERT' command converts Applesoft programs that contain the above commands into standard Applesoft by replacing the structured-programming commands with appropriate 'GOTO' statements. The APLUS '&LIST' command automatically indents listings to clarify the logic flow inside a program. APLUS automatically checks for logic errors each time the Applesoft program is listed and allows start/stop/continue control of APLUS listings. APLUS also provides a separate list of all 'named procedures' used in a program. APLUS allows new Applesoft programs to be created without entering any 'GOTO's or 'GOSUB's. These Applesfot-Plus programs are then significantly easier to develop, maintain, and understand that 'regular' Applesoft programs. APLUS can also be used to maintain existing Applesoft programs without special conversion.

Price: **$25.00**
includes: Cassette or disk with instructions
Available: Sensible Software
P.O. Box 2395
Dearborn, MI 48123

Name: **Integer BASIC Floating Point Interface (2.5K)**
System: **APPLE II**
Memory: **16K or more**
Language: **Machine Language**
Hardware: **Basic Apple II**

Description: The Integer BASIC Floating Point Interface, or IBFPI, is an integrated set of machine language routines which allows the user to indirectly use the Apple II Floating Point Utility Routines. The first eight variables defined in an Integer BASIC program allow floating point variables and arrays to be referenced from within an Integer BASIC program. IBFPI also includes utility routines for floating point exponention, input, and output. IBFPI FP output allows Fortran-like field widths. Arithmetic errors are processed automatically, and when an error is detected, an error message is printed and the current Integer BASIC line is displayed. The eight-page documentation includes features, background, program cassette operation, programming, page zero usage, error messages, structure, and notes. A demonstration program is included and is explained in the operation part of the documentation.

Copies: **7 delivered**
Price: **$8.95** postpaid
Includes: Cassette and documentation
Author: **Harry L. Pruetz**
Available: Microspan Software
P.O. Box 9692
Austin, TX 78766

Name: **Restaurant Food/Beverage Analysis and Menu Pricing**
System: **APPLE II**
Memory: **16K**
Language: **APPLESOFT II (ROM or RAM)**

Description: A self-prompting program that establishes menu prices of virtually any food/liquor item. Predetermined, and industry proved, percentages in the program define what the menu price should be in order to make an acceptable profit. The program may be utilized both for initiating a new or revising an existing menu. Re-evaluates existing menu prices and indicates what present food/liquor costs are. Takes the guess work out of menu development. No intelligent restauranteur should be without this aid.

Price: **$14.95 Diskette, $9.95 Cassette, $5.95 Listing,** plus $1.00 postage and handling.
Author: **M. Goldstein**
Available: Mind Machine, Inc.
31 Woodhollow Lane
Huntington, N.Y. 11743

Name: **Disk Utilities**
System: **APPLE II**
Memory: **48K with APPLESOFT ROM**
Language: **APPLESOFT/MACHINE**

Description: Disk Utilities is a set of 3 programs: One Drive Copy, Disk Statistics, and Patch. One Drive Copy allows disks to be copied on a system with only one disk drive. Disk Statistics displays the unused sectors of a disk as a number and a percentage of the total. Patch is a powerful tool that allows the reading, displaying (in ASCII and HEX), modification and writing of any sector on a disk.

Price: **$19.95** on diskette with user manual.
Author: **Hal Clark**
Available: ON-GOING IDEAS
P.O. Box 132
Rosemount, MN 55068

MN residents please buy at your local APPLE dealers.

Name: **AIM Microchess**
System: **AIM 65**
Memory: **2K**
Language: **Assembly**

Description: An AIM version of Microchess, Peter Jennings' original chess program for the 6502. This version features several keyboard selectable speeds, a chess clock, optional printout of the current chessboard, display of moves in standard chess notation, and more. A great way to "show off" your AIM, as well as a means to learn more about using your AIM since source listings are provided.

Copies: **AIM version, just released. KIM version, thousands!**
Price: **$15.00**
Includes: Cassette tape object, operating instructions, commented source listing.
Authors: Mel Evans - AIM Version
Peter Jennings - Original
Available: MICRO Software
P.O. Box 6502
Chelmsford, MA 01824

Name: **Micro Memo**
System: **APPLE II**
Memory: **48K**
Languagez; **RAM or ROM Applesoft**
Hardware: **Optional**—Mountain Hardware Clock (any slot) and/or any APPLE compatible printer

Description: Micro Memo is a powerful "desk calendar" program. It can handle one-time, weekly, monthly, semi-annual, and annual reminders. Monthly reminders may be for fixed dates (e.g., the 15th of the month) or "floating " dates (e.g., the 1st Saturday of every month). Each reminder allows you the choice of 1 week, 2 week or 1 month advance notice, so the system can remind you ahead of time to prepare for meetings, purchase birthday presents, make reservations, etc. The program will print out or display any day's or week's reminders, including most major holidays. This is a "perpetual" calendar which automatically creates new months with all appropriate reminders (birthdays, anniversaries, monthly meetings, etc.) as past months are dropped. The system holds a full year's reminders (beginning with any month) on one disk.

Price: **$39.95**
Includes: Disk with program and 6 pages of documentation, including information on custom modifications.
Author: **Barney Stone**
Available: STONEWARE
Microcomputer Software
P.O. Box 7218
Berkeley, CA 94707

Name: **IBM PRINT**
System: **APPLE II or APPLE II PLUS, Disk II and IDS 440 Printer**
Memory: **16K with ROM—32K without**
Language: **APPLESOFT II**

Description: IBM Print is a simple utility program for printing "TEXT" files with ANSI standard carriage control characters in column one of the records. This capability allows the user to create files for printing with overprint and paging capabilities using any text editor or program. The program is most useful for local printing of large files created on main-frames and moved to the APPLE using the terminal communications program: MOVE 370. This technique allows the user to create large print files using IBM's very powerful word processing systems, move them to the APPLE, and then print them locally. The program is easy to use and easy to modify for other brands of printers.

Price: **$20.00**
Includes: One diskette and program
Author: **Gary M. Grandon, Ph.D.**
Available: Rosen Grandon Associates
296 Peter Green Road
Tolland, CT 06084

Name: **Wilderness Campaign**
System: **APPLE II**
Memory: **48K**
Language: **Integer Basic**

Description: Wilderness Campaign is a game of high adventure in which you undertake a crusade to free the kingdom of Draconia from the Evil Necromancer that is tyrannizing it. As you direct your party across the high resolution graphics map of Draconia, you must overcome obstacles, defeat hostile inhabitants, survive various natural hazards (avalanches, quicksand, etc.) and explore numerous tombs, temples, castles, and ruins in search of gold and magical devices. When treasure is found, you will go to nearby villages to hire men and purchase weapons, armor, and assorted useful supplies. The supplies and any magical devices that you find will aid you in your ultimate quest: to find the ancient weapons of power required to defeat the Necromancer. Once you have found the required magical weapon and have gathered and equipped a suitable army, you are ready to attack the fortress of the Necromancer itself. The future of Draconia rests on your shoulders.

Copies: **Many**
Price: **$15.00 cassestte, $17.50 disk** (WA residents add 5.3% sales tax)
Author: **Robert C. Clardy**
Available: Synergistic Software
5221—120th Ave. S.E.
Bellevue, WA 98006
(206)641-1917

Name: **MAE Development Software**
System: **32K ROM PET and 2040 Disk Drive**
Memory: **10K**
Language: **Machine Language**

Description: A new Assembler/Editor and associated development software to be used for developing programs in assembly language on the new ROM 32K PET and 2040 Disk Drive. No tape is supported. User has option of connecting an extgernal CRT or TTY to obtain 80 column display operation. Features include MACROS, Conditional Assembly, and Interactive Assembly. The MAE ASSM/TED occupies 10K memory starting at $5000 and handles labels up to 31 characters. Includes relocating loader plus a copy of the loader in relocatable form so it can be relocated practically anywhere in RAM memory.

Copies: **Just Released**
Price: **$169.95** postpaid in U.S.—requires completion of software license agreement.
Includes: Diskette and Manual
Author: **C.W. Moser**
Available: Eastern House Software
3239 Linda Drive
Winston-Salem, N.C. 27106

Name: **One-Arm Bandit**
System: APPLE II
Memory: **32K**
Language: **Interger Basic**
Hardware: **APPLE II (32K), Integer Basic, Video Monitor or TV**

Description: One-Arm Bandit is a slot machine program for one to four players. It uses a combination of text graphics, low-res color graphics and sound effects to display a realistic one arm bandit. Pay off odds are based on those of a real slot machine. The program also displays many personalized messages and keeps track of each player's winnings or losses. See and hear the wheels turn when you pull the bandit's arm. Three "ORANGES"—YOU WIN!.

Price: **$9.95** for cassette, **$14.95** for disk (Listing included)
Authors: **Ken and Dawn Ellis**
Available: Progressive Computer Software
405 Corbin Road
York, PA 17403

Name: **ROSTER**
System: **APPLE II**
Memory: **48K**
Language: **APPLESOFT II**
Hardware: **APPLESOFT ROM Card, Disk II, Printer**

Description: A general purpose disk-based record-keeping program for teachers at all levels. Allows instructors to create and change class rosters, label, enter and change test or assignment scores, sort roster based on student number, student name, or rank in class, assign character or numeric grades based on any of five criteria (raw score, percent, rank, percedntile rank, or z-score), and list scores, totals (or averages), and/or grades according to any of these options. The program will (at the instructor's option) automatically weight each score's contribution to the student's cumulative total (or mean), and/or drop the lowest (weighted or unweighted) score from among a selected group of scores prior to grade assignment. Two separate list formats are available. A class roster list prints the name of the class, section, term, etc., student numbers and any or all of the following: student names, individual scores (as raw scores, percents, ranks, percentile ranks, or z-scores), totals (or means) of individual scores (using the weighting or drop options, if requested), and assigned grades (according to user-entered grading scale). Means and standard deviations for each selected item are printed automatically. The individualized student list prints any or all of the above statistics for each test or assignment separately (particularly useful for student or parent consultation). Program is password protected (you enter your own password).

Copies: **Just released**
Price: **$39.95**
Includes: Software on disk, listing, documentation, and user's manual
Available: **Dr. Douglas Eamon**
105 West Oak Street
Albion, MI 49224

Name: **Higher Graphics**
System: **APPLE II**
Memory: **32K**
Language: **Integer Basic**
Hardware: **Disk Drive**

Description: A collection of programs and shape tables that lets any programmer create detailed and beautiful high resolution displays and animation effects. Make your programs come alive by utilizing the full graphical capabilities of the Apple II. Package contains: Shape Maker— create, correct, or delete shapes, start new shape tables or add to existing ones, display any/all shapes with any scale or rotation at any time. Table Combiner—pull shapes from existing general purpose tables and add the ones you want. Screen Creator—place your shapes on the high-res screen, add areas of color and text to make detailed displays etc. Shapes—four shape tables with over 100 shapes are provided. High Res Text—how to use high resolution graphics in your program. Animation effects and display techniques.

Copies: **Many**
Price: **$25.00** (WA residents add 5.3% sales tax)
Author: **Robert C. Clardy**
Available: Synergistic Software
5221 —120th Avenue,S.E.
Bellevue, WA 98006

Name: **PET RABBIT**
System: **16K or 32K New ROM PET**
Memory: **2K**
Language: **Machine Language**

Description: Provides 12 commands which can be executed in Basics direct mode plus provision of automatic repeat of any key (including cursor control keys) held down for 0.5 seconds. Rabbit provides fast load and save commands (38 seconds versus 2 minutes 44 seconds for PET to record 8K memory), an exhaustive memory test, convert hex to decimal and vice versa, plus more. Specify memory location as: $3000, $3800, $7000, or $7800.

Copies: **Just Released**
Price: **$29.95 postpaid**
Includes: Manual and Cassette
Authors: **J.R. Hall and C.W. Moser**
Available: Eastern House Software
3239 Linda Drive
Winston-Salem, N.C. 27106

Name: **Matrix Manipulator**
System: **APPLE II or APPLE II Plus**
Memory: **32K Minimum**
Language: **ROM Applesoft**
Hardware **Disk II (opt.)**
Printer (opt.)

Description: Matrix Manipulator is an interactive program having the following modes; add, subtract, multiply, invert, transpose, scalar multiply, square root, orthonormalization, row reduce, column augment, input, edit, display/print, to/from disk, and 11 other modes. Matrix names and sizes are user definable, typified by 15 (32K) or 40 (48K) 10x10 matrices in use at once with DOS active. User's guide explains modes and applications to linear system solutions, etc. Program is supplied in two versions, one with in-line instructions.

Price: **$24.95 disk**
$22.95 tape plus 4.5% Ohio tax in Ohio
Includes: Both program versions and User's Guide
Author: **Robert Rennard**
Available: SmartWare
2281 Cobble Stone Ct.
Dayton, OH 45431

Name: **MOVE 370**
System: **APPLE II or APPLE II PLUS, Disk II and Communications**
Memory: **16K with ROM—32K without**
Language: **APPLESOFT II**

Description: MOVE 370 is a telecommunications interface program for moving complete "TEXT" files to and from IBM 370 systems. The program communicates with IBM's interactive CMS EDITOR (or other IBM editors with minor modifications) to pass files to or from the IBM system from the remote APPLE II. This capability enables the user to treat the Micro as a genuine distributed processor for data-entry and other off-loaded applications. It's easy to use and easy to modify.

Price: **$20.00**
Includes: One diskette plus program
Author: **Gary M. Grandon, Ph.D.**
Available: Rosen Grandon Associates
296 Peter Green Road
Tolland, CT 06084

Software Catalogue Note

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Requires: Disk, Applesoft (ROM of RAM)

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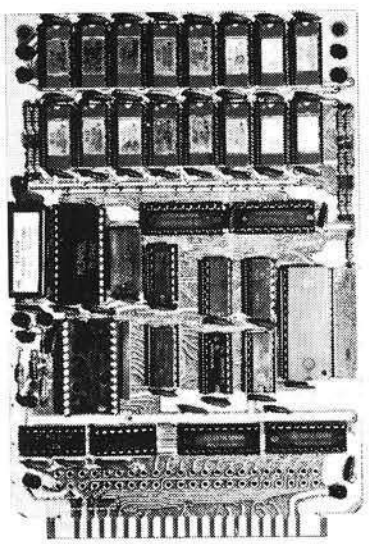

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Dr. William R. Dial
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Neulen, Bob and Golding, Val. "Change Catalog to C," pg. 30.
A short utility...but watch out playing WUMPUS with that C.

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Two programs for converting machine language to HEX Strings and writes them into program memory automatically, one each for Integer Basic and for Applesoft Basic.

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How to coax more speed out of the Apple.

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Program missing in July Apple-Cart article.

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A program that will disassemble the 6502 op-codes, printing out the op-code, address, data, all in hex and the mnemonics and addressing mode.

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Discussion of the use of the Apple II in school computer programs.

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Maintaining accurate grades in school computer systems.

Tubb, Philip. "Q and A - The 'Tiny' Interpreter Exercise," pg. 161-176.
Discussion of Applesoft Basic.

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Discussion of the "Basic Programmer's Toolkit, the Structure of Basic, encrypted messages on the PET.

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Discussion of new model PETs, etc.

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Control individual pixels on the PET screen with the Visible Memory board, and PET interface.

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Procedure for visible loading of a program from cassette tape.

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Routine to reset the DATA pointer to the beginning of any DATA line.

Zimmermann, Mark, "ROM Subroutines," pg. 11.
Some of the ROM subs of the PET are revealed.

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Seven routines including a demo.

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MT6671 is a machine-language monitor program incorporating a single-step trace feature.

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Machine-language plot routine which is faster than an equivalent Basic routine.

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How the CB2line of the PET's VIA chip (6522) can be used for generating musical tones.

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MTEST is a Non-destructive Memory test.

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The modular approach to programming encourages the use of common routines in different programs.

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Reprinted from MICRO and updated by Mark Crosby.

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A way to interrupt the commercial program, Apple Manor, and save data so that it can be resumed later.

Moon, John L., "APPLE Programming With Style," pgs. 4-5.
How to structure a program, add a menu, etc.

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Simpson, Rick, "Introduction to Machine Language Programming," pgs. 1-5.
The internal structure of the 6502 itself is discussed.

Landereau, Terry, "What's the Difference," pg. 7.
Discusses the differences in the terms assembler, interpreter, compiler, source code, object code, etc. for the Apple.

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A version modified for the Programmer's Aid ROM No. 1 of the Apple.

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pg. 13.
Short listing—the title tells it all.

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Simple hardware mod. for the Apple.

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Simple hardware mod to move the cursor faster on the Apple.

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With a simple interface and a short application program the KIM-1 can send any of three messages entered into memory.

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By using a specially electrified chessboard, the KIM-1 can be used, avoiding keyboard entry of moves.

O'Haver, T. C., "A Similarity Comparator for Strings," pgs. 58-60.
A program comparing strings or doing searches reports 'best' match if no exact match is found. In OSI Microsoft Basic.

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Hardware and two software routines.

Powers, William T., "The Nature of Robots: Part 4: Looking for Controlled Variables," pgs. 96-112.
An Apple II graphics program is given to simplify a control-variable simulation.

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Sparks, Paul W., "An Inexpensive Printer Option," pg. 3.
Interfacing the SWPTC PR-40 printer with the PET.

Busdiecker, Roy, "6502 Relocating Macro Assembler/Test Editor 1.0," pgs. 7-8.
A review of a PET program.

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Discusses the PET ROM Monitor, the care of cassettes, renumber program, etc.

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Discussion of PETFORTH and other versions of Forth.

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Illustration of the many ways a program can be improved.

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The second in a series of articles on computer arithmetic.

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Short utility for the Apple II.

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A list of Variables used by Basic and Integer Basic Subroutines for the Apple.

Hertsfeld, Andy, "Text File Mover," pg. 4.
How to get a text file from one disk to another on the Apple.

Staff, "Super HI-RES," pg. 4.
A short listing for the Apple Hires Graphics.

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Analyzes data for number of responses in each category, etc.

Paymar, Dan, "Disc Access Utility," pgs. 9-10.
Allows you to dump the contents of any specified sector and track. Useful for recovering crashed disks, on the Apple.

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Description of routines and registers affected by calling the routine.

Crosby, Mark, "Changing 'Catalog' to 'C'," pg. 12.
Two short listings for Apple DOS 3.1 and 3.2.

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Short Applesoft routine for the Apple II.

Staff, "Use of Control Y with Parameter on the Apple," pg. 14.
Demo of Control Y and the Apple Paddles.

Staff, "Statistics Programs," pg. 15.
A routine for the Hello program for the Apple that will bring up a menu and allow a given program to be selected. Example is with the Osborn list of statistics programs.

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Staff, "Documentation Library," pgs. 3-9.
In addition to maintaining a large program library, The Apple Pi user Group of Denver, CO has published an extensive list of User Group publications and Lists of documentation of Apple programs available for copying.

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Locate stars with the Apple.

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Adjust the speed of your Apple II disk drive.

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A few simple changes of variables will insure that B/BSTAT will work on Apple DOS 3.2.

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Add BEEP, BOOPand ZONK sounds to your KIM p-rograms.

Leedom, Robert, "Baseball for the KIM," pgs. 10-11.
A video style action game for the KIM-1.

McKenna, Sean, "Language Lab," pgs. 12-19.
An Editor for Microsoft Basic.

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Add a cassette interface and User function to Focal 65-E.

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This routine makes KIMs, LEDs another output device.

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How to get Tom Pitman's Tiny Basic to work with the KIM-1/TVT-6 combination.

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A routine to invert the state of the SYM speaker, producing an audible tone.

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How to make the AIM 65 run at MHz; AIM and KIMSI hints; etc.

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Hints on using the AIM Tape interface.

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How to take advantage of the large supply of KIM software using your OSI system.

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A PET Basic program for plotting.

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Let the PET move it—this article tells how.

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A high speed version of the game of LIFE. For the Apple.

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A 100 KHz event timer using the on-board 6532 can handle up to 50 elapsed time intervals or successive timed events.

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How your micro can assist program development for other machines.

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A tutorial on HIRES shapes with several demo listings.

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A tutorial on the famous Shapes program of Apple Hires.

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A drastic and probably fatal solution to overheated PET ROMs.

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This program lists the Apple II DOS Commands and their Memory locations.

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The reviewer gives this program high scores for quality and ease of use, but there are restrictions in format.

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Modification of this popular Apple program for hard copy.

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A series of subroutines for conditional and unconditional delays for Integer or Applesoft Basic.

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Measure capacitance 1pf to 999.999mfd.

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You can have machine language and BASIC too in your PET. The machine language is up to 500 times faster.

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The Apple Programmer's AID ROM comes with an excellent 96 page manual.

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A workshop for teachers using strings to introduce BASIC statements and programming techniques.

572. Southeastern Software Newsletter, Iss. 12 (September 1979).

Carpenter, Chuck. "Indexing Fundamentals: Part I," pg. 2.
A tutorial on absolute addressing, to be followed by another article on indirect addressing, and symbolic addressing.

Burnett, Carol. "LO-RES Graphics Program," pg. 4-5.
Graphics with sound.

Anon. "Formatting $ and Cents," pg. 5.
A useful utility.

Anon. "Gas and Mileage Chart," pg. 6-7.
Uses variables of miles per gallon, price per gallon, mileage and cost.

573. Recreational Computing 8, No 2 (Sept/Oct 1979)

Wells, Arthur, J. "An Apple PILOT Interpreter," pg. 24-27.
How to write and use programs written in PILOT using a language interpreter program on your Apple II.

Saal, Harry. "SPOT," pg. 54-55.
New games for the PET, etc.

Day, Jim. "Graphic Triples for Apple II," pg. 56.
Program generates and displays Pythagorean triples.

574. Stems from the Apple 2, Iss. 9. (Sept. 1979)

Hoggatt, Ken. "Ken's Korner," pg. 2.
Quick test to see which DOS (3.1 or 3.2) you have on disk. Misc. other hints and kinks.

Anon. "Faster than a Speeding Byte," pg. 4.
All about the speed of microprocessors. The OSI Challenger (6502) is the only known production micro on the market to run faster than an Apple II.

Keyes, Patricia. "A String$ Expression Compiler for Applesoft," pg. 8.

575. Dr. Dobbs Journal 4, Iss. 9, No 39 (Oct. 1979)

Diaz, Robert D. "Page List for the Apple," pg. 19-21.
Program to permit listing one page at a time.

Ratliff, Gary. "Just Poking Around with my PET," pg. 22-23.
Method of dumping memory to the screen and how to view the PET Basic Interpreter.

Wheeler, Steve. "Quick and Dirty Routines for the Sweet-16," pg. 24-25.
A modification to the cassette version of the S-C Assembler II which gives it the capability to recognize and correctly assemble SWEET-16 mnemonics.

Morganstein, David. "David and Goliath," pg. 30-31.
How to set up the OSI 430 Board RS232 interface to hook up a modem and phone lines.

Tan, B.T.G. "Common Instructions of the 6800 and 6502," pg 38-39.
A tutorial comparing the instruction sets of two microprocessors.

576. ABACUS II Newsletter, Iss. 9/10 (Sept/Oct 1979)

Luebbert, Prof. William F. "What's Where in the Apple," pg. 1-8.
A very comprehensive memory map (reprinted from MICRO).

Anon. "Real Handy Data," pg. 9-11.
A series of Routines for the Apple, Tables of Apple Data, ASCII chart, Monitor Cross reference tables, Applesoft and Integer Token charts, Applesoft Interpreter Set, Apple DOS symbol table listing, Zero page usage, Lists of Computer Clubs, Apple User Groups, etc.

577. Byte 4, No 10 (Oct. 1979)

Garber, Joseph P. "Computer Generated Maps," pg. 18.
A Hires Apple program for a map of the U.S.

578. The Seed 1, Iss. 1 (June 1979)

Willmore, Richard. "Recursive Primer," pg. 5-9.
A tutorial on block-structured languages and their most powerful feature, recursion, which allows a program to create new copies of itself as the problem demands.

Knaster, Scott. "Controlling Control-C," pg. 9.
An Applesoft program for use in turn-key systems which disables the Control C function of the Apple.

Anon. "Illegal Line Numbers," pg. 10.
How to use illegal line numbers in a program, for the Apple. Works only on Cassettes. For DOS use 9600 instead of BFFF.

Anon. "Nifty Self Run," pg. 11.
How to make any Applesoft program self-starting as it is loading.

Anon. "Apple Pi Library," pg. 12-15.
A list of 472 programs for the Apple.

Nelsen, Rodney. "String Sorter," pg. 15.
This program alphabetizes your strings on the Apple.

579. The Seed 1, No 2 (July 1979)

Taylor, T.N. "Apple Groups Publications," pg. 5.
A list of Apple User Group Publications.

Willmore, Richard. "Reclusive Primer," pg. 5-7.
A tutorial on block-structured languages.

Willmore, Richard. "Tools for Exploring a Frontier," pg. 8-12.
All about compilers, XPL, PASCAL, Assemblers, File systems, Apple DOS, Floppy File Systems, etc.

Taylor, Terry, "Apple Pi Library," pgs. 13-20.
863 Programs are listed, for the Apple.

Anon, "Apple Pascal," pgs. 3-6.
A well written description of what to do when you get your Pascal package.

Taylor, Terry, "Apple Pi Library," pgs. 7-9.
Some 400 new programs are listed bringing the total to over 1400.

Brown, Donald, "The $7.00 Two-Apple Hookup," pgs. 9-10.
All about the SART Routines that permit extremely cheap communications between two Apples.

Anon, "Information Processing: Surviving a Microcomputer Shift," pgs. 12-13.
Reprinted from Business Week. A discussion with Computer marketing experts. How the Apple and TRS-80 have changed the small computer picture.

580. Compute, Iss. 7 (Fall 1979)

Hulon, Belinda and Hulon, Rick, "Sorting Sorts: A Programming Notebook," pg. 7.
Several Sort methods are evaluated including Selection Sort, Bubble Sort, and Shell Sort. In a later article Machine Language sorts will be discussed.

Lindsay, Len, "Three Word Processors," pgs. 13-20.
An overview of three word processors for the PET.

Byrd, J.S., "Microcomputers for Nuclear Instrumentation," pgs. 24-26.
Describes the use of PET microcomputers in handling several applications at the Savannah River Laboratory.

Herman, Harvey, B., "Tokens Aren't Just for Subways," pgs. 29-30.
A convenient method to list Microsoft Basic Tokens for the PET.

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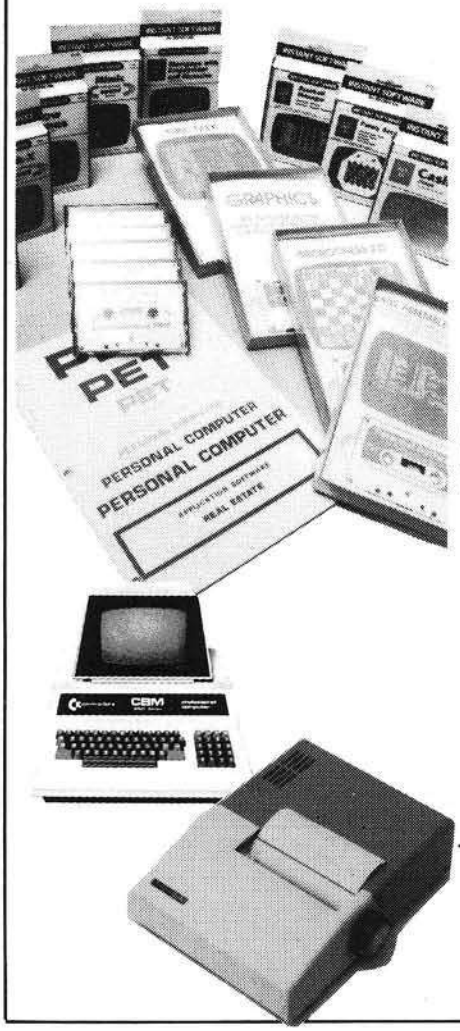

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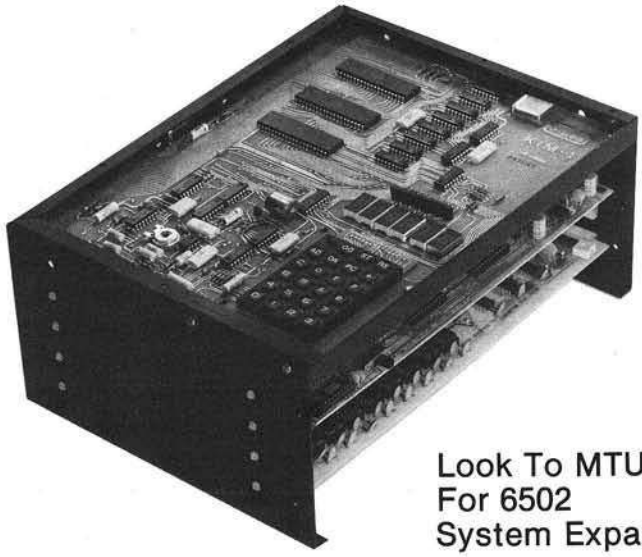

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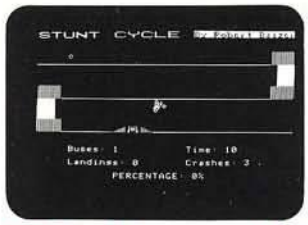

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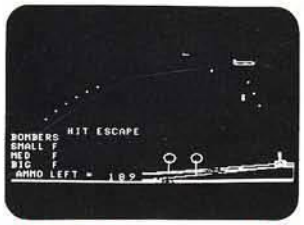

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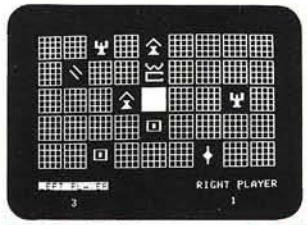

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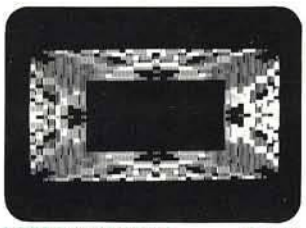

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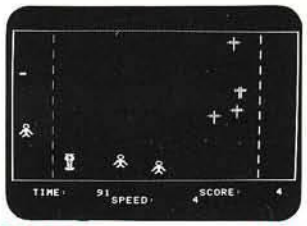

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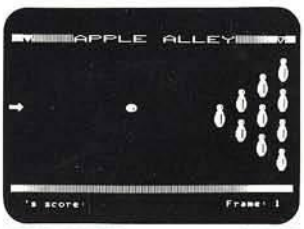

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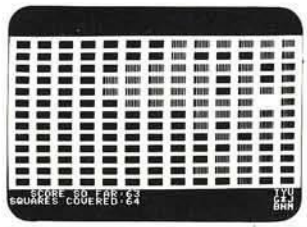

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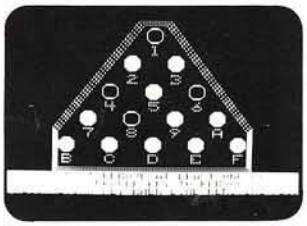

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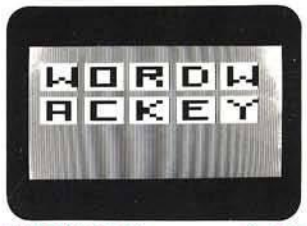

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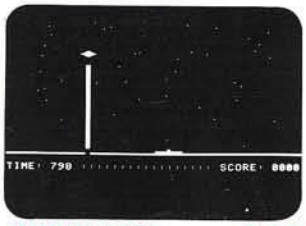

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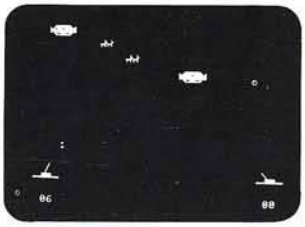

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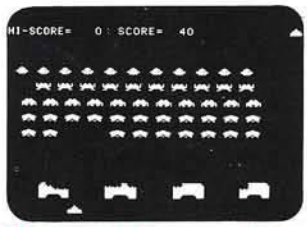

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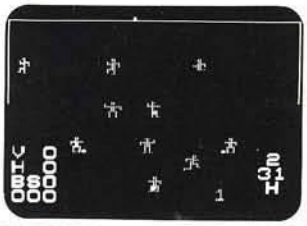

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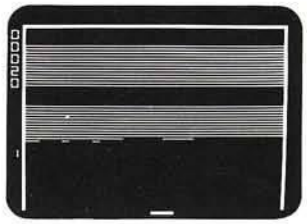

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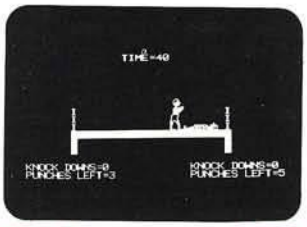

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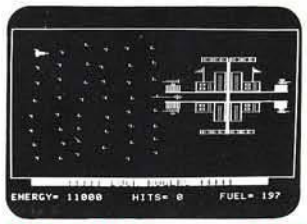

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